

Electrical Engineering Department
Engineering mathematics Diploma
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Chapter One

Laplace Transforms

Contents of Chapter One

- Laplace Transform of basic functions using the definition
 - Transform of derivatives and integrals
 - Properties of Laplace Transform
 - Inverse Laplace Transform
 - Solution of linear differential equations using Laplace Transform
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-

Laplace Transforms

If $f(t)$ is a function defined for all $t \geq 0$, its Laplace transform is the integral of $f(t)$ times e^{-st} from $t = 0$ to ∞ . It is a function of s , say, $F(s)$, and is denoted by $\mathcal{L}\{f\}$; thus

$$F(s) = \mathcal{L}\{f\} = \int_0^{\infty} f(t)e^{-st} dt$$

The operation $\mathcal{L}\{ \}$ transforms $f(t)$, which is in the time domain, into $F(s)$, which is in the complex frequency domain, or simply (s -domain) where s is the complex variable ($\sigma + j\omega$)

Laplace Transforms

Evaluating Laplace transform using the definition

1. $f(t) = k$

$$F(s) = \mathcal{L}\{f(t)\} = \int_0^{\infty} f(t)e^{-st} dt = \int_0^{\infty} ke^{-st} dt$$

$$F(s) = -\frac{k}{s} [e^{-st}]_{t=0}^{t=\infty} = -\frac{k}{s} [e^{-s\infty} - e^{-s0}] = \frac{k}{s}$$

$$\mathcal{L}\{k\} = \frac{k}{s}$$

For $f(t) = 5$

$$F(s) = \int_0^{\infty} f(t)e^{-st} dt = \int_0^{\infty} 5e^{-st} dt = -\frac{5}{s} e^{-st} \Big|_0^{\infty} = \left[-\frac{5}{s} e^{-s\infty} \right] - \left[-\frac{5e^{-s0}}{s} \right] = \frac{5}{s}$$

Laplace Transforms

2. $f(t) = t$

$$F(s) = \mathcal{L}\{f(t)\} = \int_0^{\infty} f(t)e^{-st} dt = \int_0^{\infty} te^{-st} dt$$

$$\int u dv = uv - \int v du$$

By letting $u = t$ and $dv = e^{-st} dt$ we find

$$\int te^{-st} dt = -\frac{1}{s}te^{-st} + \frac{1}{s} \int e^{-st} dt = -\frac{1}{s}te^{-st} - \frac{1}{s^2}e^{-st}$$

$$F(s) = \left[-\frac{1}{s}te^{-st} - \frac{1}{s^2}e^{-st} \right]_{t=0}^{t=\infty} = \frac{1}{s^2}$$

$$\mathcal{L}\{t\} = \frac{1}{s^2}$$

In general,

$$\mathcal{L}\{t^n\} = \frac{n!}{s^{n+1}}$$

Laplace Transforms

3. $f(t) = e^{-at}$

$$F(s) = \mathcal{L}\{f(t)\} = \int_0^{\infty} f(t)e^{-st} dt = \int_0^{\infty} e^{-at} e^{-st} dt$$

$$F(s) = \int_0^{\infty} e^{-(a+s)t} dt = \left[\frac{-e^{-(a+s)t}}{a+s} \right]_{t=0}^{t=\infty}$$

$$F(s) = \left[\frac{-e^{-(a+s)\infty}}{a+s} + \frac{e^{-(a+s)0}}{a+s} \right] = \frac{1}{a+s}$$

$$\mathcal{L}\{e^{-at}\} = \frac{1}{s+a}$$

Laplace Transforms

4. $f(t) = e^{at}$

$$F(s) = \mathcal{L}\{f(t)\} = \int_0^{\infty} f(t)e^{-st} dt = \int_0^{\infty} e^{at}e^{-st} dt$$

$$F(s) = \int_0^{\infty} e^{-(s-a)t} dt = \left[-\frac{e^{-(s-a)t}}{s-a} \right]_{t=0}^{t=\infty}$$

$$F(s) = \left[\frac{-e^{-(s-a)\infty}}{s-a} + \frac{e^{-(s-a)0}}{s-a} \right] = \frac{1}{s-a}$$

$$\mathcal{L}\{e^{at}\} = \frac{1}{s-a}$$

Laplace Transforms

5. $f(t) = \cos \omega t$

$$\mathcal{L}\{f(t)\} = \int_0^{\infty} \cos \omega t e^{-st} dt = \int_0^{\infty} \left[\frac{e^{j\omega t} + e^{-j\omega t}}{2} \right] e^{-st} dt$$

$$= \frac{1}{2} \left[\int_0^{\infty} e^{j\omega t} e^{-st} dt + \int_0^{\infty} e^{-j\omega t} e^{-st} dt \right]$$

$$= \frac{1}{2} [\mathcal{L}\{e^{j\omega t}\} + \mathcal{L}\{e^{-j\omega t}\}]$$

$$= \frac{1}{2} \left[\frac{1}{s-j\omega} + \frac{1}{s+j\omega} \right] = \frac{s}{s^2 + \omega^2}$$

$$\mathcal{L}\{\cos \omega t\} = \frac{s}{s^2 + \omega^2}$$

Laplace Transforms

6. $f(t) = e^{-at} \sin \omega t$

$$\begin{aligned} \int_0^{\infty} e^{-at} * \sin(\omega t) * e^{-st} * dt &= \int_0^{\infty} e^{-at} * \frac{e^{j\omega t} - e^{-j\omega t}}{2j} * e^{-st} * dt \\ &= \frac{1}{2j} \int_0^{\infty} [e^{-at+j\omega t} e^{-st} - e^{-at-j\omega t} e^{-st}] * dt \\ &= \frac{1}{2j} \left[\frac{1}{(s+a) - j\omega} - \frac{1}{(s+a) + j\omega} \right] \end{aligned}$$

$$\mathcal{L}\{e^{-at} \sin \omega t\} = \frac{\omega}{(s+a)^2 + \omega^2}$$

Laplace Transforms

7. $\mathcal{L}\left\{\frac{df(t)}{dt}\right\}$

$$\mathcal{L}\left\{\frac{df(t)}{dt}\right\} = \int_0^{\infty} \frac{df(t)}{dt} e^{-st} dt$$

By using $\int u dv = uv - \int v du$

$$u = e^{-st} \implies du = -s e^{-st} dt$$

$$dv = \frac{df(t)}{dt} dt \implies v = f(t)$$

$$\begin{aligned} \int_0^{\infty} \frac{df(t)}{dt} e^{-st} dt &= [e^{-st} f(t)]_{t=0}^{t=\infty} + s \int_0^{\infty} f(t) e^{-st} dt \\ &= 0 - f(0) + s \int_0^{\infty} f(t) e^{-st} dt \end{aligned}$$

$$\mathcal{L}\left\{\frac{df(t)}{dt}\right\} = sF(s) - f(0)$$

Laplace Transforms

We can extend the previous to show

$$\mathcal{L}\left\{\frac{d^2 f(t)}{dt^2}\right\} = s^2 F(s) - sf(0) - f'(0)$$

$$\mathcal{L}\left\{\frac{d^3 f(t)}{dt^3}\right\} = s^3 F(s) - s^2 f(0) - sf'(0) - f''(0)$$

In general

$$\mathcal{L}\left\{\frac{d^n f(t)}{dt^n}\right\} = s^n F(s) - s^{n-1} f(0) - s^{n-2} f'(0) - \dots - f^{(n-1)}(0)$$

Laplace Transforms

8. $\mathcal{L}\left\{\int f(t)dt\right\}$

$$\mathcal{L}\left\{\int f(t)dt\right\} = \frac{F(s)}{s} + \frac{1}{s} \left[\int f(t)dt \right]_{t=0}$$

$$\mathcal{L}\left\{\int_0^t f(t)dt\right\} = \frac{F(s)}{s}$$

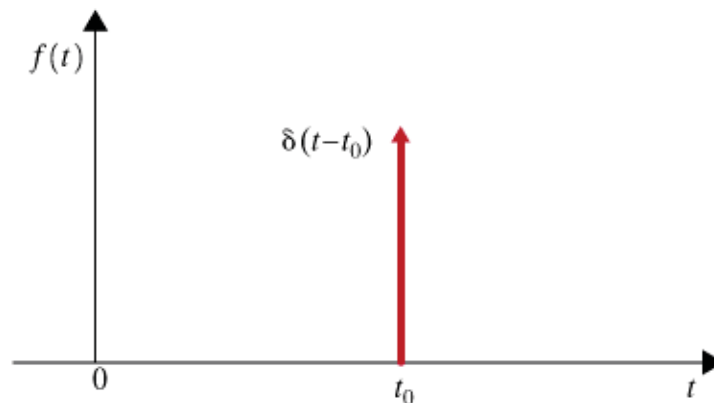
Laplace Transform Table

Function, $f(t)$	Laplace transform, $F(s)$	Function, $f(t)$	Laplace transform, $F(s)$
1	$\frac{1}{s}$	$e^{-at} \cos bt$	$\frac{s+a}{(s+a)^2 + b^2}$
t	$\frac{1}{s^2}$	$\sinh bt$	$\frac{b}{s^2 - b^2}$
t^2	$\frac{2}{s^3}$	$\cosh bt$	$\frac{s}{s^2 - b^2}$
t^n	$\frac{n!}{s^{n+1}}$	$e^{-at} \sinh bt$	$\frac{b}{(s+a)^2 - b^2}$
e^{at}	$\frac{1}{s-a}$	$e^{-at} \cosh bt$	$\frac{s+a}{(s+a)^2 - b^2}$
e^{-at}	$\frac{1}{s+a}$	$t \sin bt$	$\frac{2bs}{(s^2 + b^2)^2}$
$t^n e^{-at}$	$\frac{n!}{(s+a)^{n+1}}$	$t \cos bt$	$\frac{s^2 - b^2}{(s^2 + b^2)^2}$
$\sin bt$	$\frac{b}{s^2 + b^2}$	$u(t)$ unit step	$\frac{1}{s}$
$\cos bt$	$\frac{s}{s^2 + b^2}$	$u(t-d)$	$\frac{e^{-sd}}{s}$
$e^{-at} \sin bt$	$\frac{b}{(s+a)^2 + b^2}$	$\delta(t)$	1
		$\delta(t-d)$	e^{-sd}

Laplace Transforms

Example:

Find the Laplace transform of following impulse function



$$\mathcal{L}\{\delta(t - t_0)\} = \int_0^{\infty} \delta(t - t_0) e^{-st} dt = e^{-st_0}$$

Laplace Transforms

Other Examples

$f(t)$	$F(s)$	$f(t)$	$F(s)$	$f(t)$	$F(s)$
(a) t^3	$\frac{6}{s^4}$	(e) $\cos(t/2)$	$\frac{s}{s^2 + 0.25}$	(h) $t \sin 4t$	$\frac{8s}{(s^2 + 16)^2}$
(b) t^7	$\frac{7!}{s^8}$	(f) $\sinh 3t$	$\frac{3}{s^2 - 9}$	(i) $e^{-t} \sin 2t$	$\frac{2}{(s + 1)^2 + 4}$
(c) $\sin 4t$	$\frac{4}{s^2 + 16}$	(g) $\cosh 5t$	$\frac{s}{s^2 - 25}$	(j) $e^{3t} \cos t$	$\frac{s - 3}{(s - 3)^2 + 1}$
(d) e^{-2t}	$\frac{1}{s + 2}$				

Properties of Laplace Transforms

- Linearity

$$\mathcal{L}\{af(t) \pm bg(t)\} = a\mathcal{L}\{f(t)\} \pm b\mathcal{L}\{g(t)\}$$

- First shift theorem (Frequency shift theorem)

$$\mathcal{L}\{e^{\pm at} f(t)\} = F(s \mp a)$$

- Second shift theorem (Time shift theorem)

$$\mathcal{L}\{f(t - a)u(t - a)\} = e^{-as} F(s)$$

Properties of Laplace Transforms

- Time scaling

$$\mathcal{L}\{f(at)\} = \frac{1}{a} F\left(\frac{s}{a}\right)$$

- Multiplication by time

$$\mathcal{L}\{t^n f(t)\} = (-1)^n \frac{d^n F(s)}{ds^n}$$

Properties of Laplace Transforms

Examples:

Determine the Laplace transform of

a) $f(t) = t^3 - 3e^{-4t} + \sin 2t$

b) $f(t) = (1 - e^{-3t}) \cos t - \frac{t^4}{4}$

c) $f(t) = e^{-5t} t^3$

d) $f(t) = (t - 2)^2 u(t - 2)$

e) $f(t) = t g'(t)$

Properties of Laplace Transforms

a)

$$\begin{aligned}\mathcal{L}\{t^3 - 3e^{-4t} + \sin 2t\} &= \mathcal{L}\{t^3\} - 3\mathcal{L}\{e^{-4t}\} + \mathcal{L}\{\sin 2t\} \\ &= \frac{6}{s^4} - \frac{3}{s+4} + \frac{2}{s^2+4}\end{aligned}$$

b)

$$\begin{aligned}\mathcal{L}\{f(t)\} &= \mathcal{L}\left\{\cos t - e^{-3t}\cos t - \frac{t^4}{4}\right\} \\ &= \mathcal{L}\{\cos t\} - \mathcal{L}\{e^{-3t}\cos t\} - \frac{1}{4}\mathcal{L}\{t^4\} \\ &= \frac{s}{s^2+1} - \frac{s+3}{(s+3)^2+1} - \frac{6}{s^5}\end{aligned}$$

Properties of Laplace Transforms

c) Let $g(t) = t^3$ then $G(s) = \frac{6}{s^4}$

Therefore

$$\begin{aligned}F(s) &= \mathcal{L}\{e^{-5t}t^3\} = \mathcal{L}\{e^{-5t}g(t)\} \\ &= G(s+5) = \frac{6}{(s+5)^4}\end{aligned}$$

d) Let $g(t) = t^2$ then $G(s) = \frac{2}{s^3}$

and also $g(t-2) = (t-2)^2$

Therefore

$$\begin{aligned}F(s) &= \mathcal{L}\{(t-2)^2u(t-2)\} = \mathcal{L}\{g(t-2)u(t-2)\} \\ &= e^{-2s}G(s) = \frac{2e^{-2s}}{s^3}\end{aligned}$$

Properties of Laplace Transforms

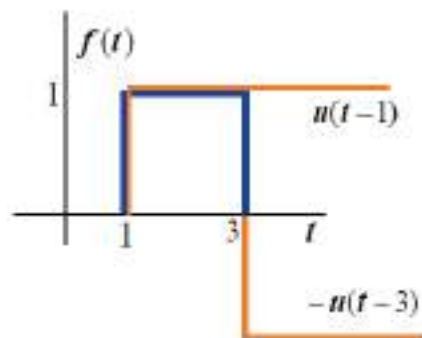
e)

$$\begin{aligned}\mathcal{L}\{tg'(t)\} &= -\frac{d}{ds}\mathcal{L}\{g'(t)\} \\ &= -\frac{d}{ds}[sG(s) - g(0)] \\ &= -[G(s) + sG'(s) - 0] \\ &= -G(s) - sG'(s)\end{aligned}$$

Properties of Laplace Transforms

Examples:

$$f(t) = \begin{cases} 1 & 1 \leq t \leq 3 \\ 0 & \text{elsewhere} \end{cases}$$



$$f(t) = u(t-1) - u(t-3)$$

$$F(s) = e^{-s} \frac{1}{s} - e^{-3s} \frac{1}{s} = \frac{1}{s} (e^{-s} - e^{-3s})$$

Properties of Laplace Transforms

Examples:

Let $u(t)$ be the unit step function. Find the Laplace transform of the ramp function

$$r(t) = tu(t)$$

Solution:

$$u(t) \leftrightarrow U(s) = \frac{1}{s}$$

$$tu(t) \leftrightarrow -\frac{d}{ds}\left(\frac{1}{s}\right) = \frac{1}{s^2}$$

$$t^2u(t) \leftrightarrow -\frac{d}{ds}\left(\frac{1}{s^2}\right) = \frac{2}{s^3}$$

By successive application of the property, one can show that

$$t^n(u(t)) \leftrightarrow \frac{n!}{s^{n+1}}$$

This result, plus linearity, allows computation of the transform of any polynomial

Properties of Laplace Transforms

Examples: Find the Laplace transform of

$$f(t) = te^{-(t-1)}u(t-1) - e^{-(t-1)}u(t-1)$$

Solution:

One can apply the time shifting property if the time variable always appears as it appears in the argument of the step. In this case as $t - 1$

$$f(t) = (t-1+1)e^{-(t-1)}u(t-1) - e^{-(t-1)}u(t-1)$$

$$f(t) = (t-1)e^{-(t-1)}u(t-1) + e^{-(t-1)}u(t-1) - e^{-(t-1)}u(t-1)$$

$$= (t-1)e^{-(t-1)}u(t-1)$$

$$tu(t) \leftrightarrow \frac{1}{s^2}$$

$$te^{-t}u(t) \leftrightarrow \frac{1}{(s+1)^2}$$

$$\therefore (t-1)e^{-(t-1)}u(t-1) \leftrightarrow \frac{e^{-s}}{(s+1)^2}$$

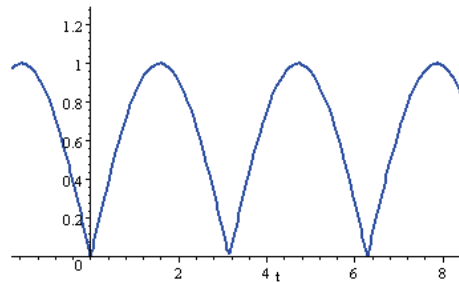
Laplace Transforms

Laplace Transform of a Periodic Function $f(t)$

The Laplace Transform of the periodic function, $f(t)$ with period p , equals the Laplace Transform of one cycle of the function, divided by $(1 - e^{-sp})$.

$$\mathcal{L}\{f(t)\} = \frac{\mathcal{L}\{f_1(t)\}}{1 - e^{-sp}}$$

Example: Full-wave rectifier of $\sin t$ is



Solution: We have

$$f_1(t) = \sin t \times [u(t) - u(t - \pi)]$$

And the period $p = \pi$.

$$\mathcal{L}\{f_1(t)\} = \mathcal{L}\{\sin t \times [u(t) - u(t - \pi)]\}$$

$$\mathcal{L}\{f_1(t)\} = \mathcal{L}\{\sin t \times u(t)\} - \mathcal{L}\{\sin(t) \times u(t - \pi)\}$$

But since $\sin t = -\sin(t - \pi)$

$$\mathcal{L}\{f_1(t)\} = \mathcal{L}\{\sin t \times u(t)\} + \mathcal{L}\{\sin(t - \pi) \times u(t - \pi)\}$$

$$= \frac{1}{s^2 + 1} + \frac{e^{-\pi s}}{s^2 + 1}$$

So the Laplace Transform of the periodic function is given by:

$$\mathcal{L}\{f(t)\} = \frac{1 + e^{-\pi s}}{(s^2 + 1)(1 - e^{-\pi s})}$$

Inverse Laplace Transform

The inverse Laplace transform of $F(s)$ is $f(t)$, i.e.

$$\mathcal{L}^{-1}[F(s)] = f(t) = \frac{1}{2\pi j} \int_{\sigma-j\infty}^{\sigma+j\infty} F(s)e^{ts} ds$$

Where \mathcal{L}^{-1} is inverse Laplace transform operator.

Examples: Find the inverse Laplace transform of

a) $\frac{2}{s^3}$

b) $\frac{2}{s^4}$

c) $\frac{1}{s^2+25}$

d) $\frac{5s-6}{s^2+9}$

e) $\frac{s+1}{(s+1)^2+4}$

f) $\frac{s}{(s+1)^2+4}$

Inverse Laplace Transform

Solutions:

From the table of Laplace Transform

$$(a) \mathcal{L}^{-1}\left\{\frac{2}{s^3}\right\} = \mathcal{L}^{-1}\left\{\frac{2!}{s^3}\right\} = t^2$$

$$(b) \mathcal{L}^{-1}\left\{\frac{2}{s^4}\right\} = \frac{2}{3!} \mathcal{L}^{-1}\left\{\frac{3!}{s^4}\right\} = \frac{1}{3} t^3$$

$$(c) \mathcal{L}^{-1}\left\{\frac{1}{s^2+25}\right\} = \frac{1}{5} \mathcal{L}^{-1}\left\{\frac{5}{s^2+5^2}\right\} = \frac{1}{5} \sin 5t$$

Inverse Laplace Transform

(d) Write $\frac{5s-6}{s^2+9} = 5\frac{s}{s^2+3^2} - 2\frac{3}{s^2+3^2}$

$$\begin{aligned}\therefore \mathcal{L}^{-1}\left\{\frac{5s-6}{s^2+9}\right\} &= 5\mathcal{L}^{-1}\left\{\frac{s}{s^2+3^2}\right\} - 2\mathcal{L}^{-1}\left\{\frac{3}{s^2+3^2}\right\} \\ &= 5\cos 3t - 2\sin 3t\end{aligned}$$

(e) $\mathcal{L}^{-1}\left\{\frac{s+1}{(s+1)^2+4}\right\} = e^{-t}\cos 2t$

Inverse Laplace Transform

(f) Since the ILT of the terms cannot be found directly from the table, we need to rewrite it as the following

$$\begin{aligned}\frac{s}{(s+1)^2+4} &= \frac{(s+1)-1}{(s+1)^2+4} = \frac{s+1}{(s+1)^2+4} - \frac{1}{(s+1)^2+4} \\ &= \frac{s+1}{(s+1)^2+2^2} - \frac{1}{2} \cdot \frac{2}{(s+1)^2+2^2}\end{aligned}$$

$$\begin{aligned}\therefore \mathcal{L}^{-1}\left\{\frac{s}{(s+1)^2+4}\right\} &= \mathcal{L}^{-1}\left\{\frac{s+1}{(s+1)^2+2^2}\right\} - \frac{1}{2}\mathcal{L}^{-1}\left\{\frac{2}{(s+1)^2+2^2}\right\} \\ &= e^{-t}\cos 2t - \frac{1}{2}e^{-t}\sin 2t\end{aligned}$$

Inverse Laplace Transform

Most of the Laplace transforms that we encounter are proper rational functions of the form

$$F(s) = \frac{P(s)}{Q(s)} = \frac{a_m s^m + a_{m-1} s^{m-1} + \dots + a_1 s + a_0}{b_n s^n + b_{n-1} s^{n-1} + \dots + b_1 s + b_0}$$

Zeros: roots of numerator

Poles: roots of denominator

Partial Fraction Expansion:

If $m < n$ and the poles are distinct

$$F(s) = \frac{P(s)}{Q(s)} = \frac{K_1}{s - p_1} + \frac{K_2}{s - p_2} + \frac{K_3}{s - p_3} + \dots + \frac{K_n}{s - p_n}$$

Inverse Laplace Transform

If $m < n$ and the poles are duplicated

$$\frac{P(s)}{(s - p_1)^r} = \frac{K_1}{(s - p_1)^r} + \frac{K_2}{(s - p_1)^{r-1}} + \frac{K_3}{(s - p_1)^{r-2}} + \dots + \frac{K_r}{s - p_1}$$

The Coefficients K_1, K_2, \dots, K_r can be found as follow

$$K_n = \frac{1}{(n - 1)!} \times \left[\frac{d^{n-1}}{ds^{n-1}} [(s - p_1)^r F(s)] \right]_{s=p_1}$$

Where $n = 1, 2, 3, \dots, r$

Inverse Laplace Transform

Examples: Find the inverse Laplace transform of

$$(a) \frac{s-8}{s(s-2)}$$

$$(b) \frac{9}{2s^2+7s-4}$$

$$(c) \frac{4s+1}{s^3+2s^2+s}$$

$$(d) \frac{7s-20}{s(s^2-4s+20)}$$

$$(e) \frac{s^2}{s^2+5s+6}$$

$$(f) F(s) = \frac{s^2+2s+3}{(s+1)^3}$$

Inverse Laplace Transform

Solutions: We use the partial fraction technique

$$(a) F(s) = \frac{s-8}{s(s-2)} = \frac{A}{s} + \frac{B}{s-2} = \frac{4}{s} - \frac{3}{s-2}$$

$$\mathcal{L}^{-1}[F(s)] = \mathcal{L}^{-1}\left[\frac{4}{s} - \frac{3}{s-2}\right] = 4 - 3e^{2t}$$

$$(b) F(s) = \frac{9}{2s^2+7s-4} = \frac{2}{2s-1} - \frac{1}{s+4} = \frac{1}{s-1/2} - \frac{1}{s+4}$$

$$\mathcal{L}^{-1}[F(s)] = \mathcal{L}^{-1}\left[\frac{1}{s-1/2} - \frac{1}{s+4}\right] = e^{t/2} - e^{-4t}$$

Inverse Laplace Transform

$$\begin{aligned} \text{(c)} \quad \mathcal{L}^{-1}\left\{\frac{4s+1}{s^3+2s^2+s}\right\} &= \mathcal{L}^{-1}\left\{\frac{4s+1}{s(s+1)^2}\right\} \\ &= \mathcal{L}^{-1}\left\{\frac{1}{s} + \frac{3}{(s+1)^2} - \frac{1}{s+1}\right\} \\ &= 1 + 3e^{-t}t - e^{-t} \end{aligned}$$

where, if we let $F(s) = \frac{1}{s^2}$, then $f(t) = t$. Hence,

$$\mathcal{L}^{-1}\left\{\frac{1}{(s+1)^2}\right\} = \mathcal{L}^{-1}\{F(s+1)\} = e^{-t}f(t) = e^{-t}t$$

Inverse Laplace Transform

$$\begin{aligned} \text{(d)} \quad \mathcal{L}^{-1}\left\{\frac{7s-20}{s(s^2-4s+20)}\right\} &= \mathcal{L}^{-1}\left\{-\frac{1}{s} + \frac{s+3}{s^2-4s+20}\right\} \\ &= \mathcal{L}^{-1}\left\{-\frac{1}{s} + \frac{s+3}{(s-2)^2+16}\right\} \\ &= \mathcal{L}^{-1}\left\{-\frac{1}{s} + \frac{(s-2)+5}{(s-2)^2+16}\right\} \\ &= \mathcal{L}^{-1}\left\{-\frac{1}{s} + \frac{s-2}{(s-2)^2+16} + \frac{5}{(s-2)^2+16}\right\} \\ &= -1 + e^{2t} \cos 4t + \frac{5}{4} e^{2t} \sin 4t \end{aligned}$$

Inverse Laplace Transform

(e)

$$\begin{aligned}\mathcal{L}^{-1}\left\{\frac{s^2}{s^2+5s+6}\right\} &= \mathcal{L}^{-1}\left\{1 - \frac{5s+6}{s^2+5s+6}\right\} \\ &= \mathcal{L}^{-1}\left\{1 - \frac{5s+6}{(s+2)(s+3)}\right\} \\ &= \mathcal{L}^{-1}\left\{1 + \frac{4}{s+2} - \frac{9}{s+3}\right\} \\ &= \delta(t) + 4e^{-2t} - 9e^{-3t}\end{aligned}$$

(f)

$$F(s) = \frac{s^2 + 2s + 3}{(s+1)^3} = \frac{K_1}{(s+1)^3} + \frac{K_2}{(s+1)^2} + \frac{K_3}{s+1}$$
$$(s+1)^3 \frac{s^2 + 2s + 3}{(s+1)^3} = (s+1)^3 \left[\frac{K_1}{(s+1)^3} + \frac{K_2}{(s+1)^2} + \frac{K_3}{s+1} \right]$$

$$s^2 + 2s + 3 = K_1 + (s+1)K_2 + (s+1)^2K_3$$

$$[s^2 + 2s + 3]_{s=-1} = [K_1 + (s+1)K_2 + (s+1)^2K_3]_{s=-1} \Rightarrow K_1 = 2$$

$$[2s + 2]_{s=-1} = [K_2 + 2(s+1)K_3]_{s=-1} \Rightarrow K_2 = 0$$

$$[2]_{s=-1} = [2K_3]_{s=-1} \Rightarrow K_3 = 1$$

$$\mathcal{L}^{-1}[F(s)] = \mathcal{L}^{-1}\left[\frac{2}{(s+1)^3} + \frac{1}{s+1}\right]$$

$$f(t) = t^2e^{-t} + e^{-t}$$

Inverse Laplace Transform

Matlab command for partial fraction Expansion:

```
num = [2 5 3 6]
den = [1 6 11 6]
```

$$\frac{2s^3 + 5s^2 + 3s + 6}{s^3 + 6s^2 + 11s + 6}$$

The command

```
[r,p,k] = residue(num,den)
```

Gives the following result

```
[r,p,k] = residue(num,den)

r =
    -6.0000
    -4.0000
     3.0000

p =
    -3.0000
    -2.0000
    -1.0000

k =
     2
```

$$2 + \frac{-6}{s+3} + \frac{-4}{s+2} + \frac{3}{s+1}$$

Inverse Laplace Transform

The Convolution Theorem:

$f(t) * g(t)$ is called as the convolution of $f(t)$ and $g(t)$,

And it is defined by

$$f(t) * g(t) = \int_0^t f(t-v)g(v)dv$$

Convolution property: $f(t) * g(t) = g(t) * f(t)$

Therefore,

$$f(t) * g(t) = \int_0^t f(t-v)g(v)dv = \int_0^t f(v)g(t-v)dv = g(t) * f(t)$$

Sometime, $f(t) * g(t)$ is denoted as $(f * g)(t)$ or simply $f * g$.

In Laplace transform

$$\mathcal{L}^{-1}\{F(s)G(s)\} = f(t) * g(t)$$

Inverse Laplace Transform

Examples: Use the convolution theorem to find the inverse Laplace transforms of the following:

$$(a) \frac{1}{(s-1)(s+2)}$$

$$(b) \frac{12}{s(s^2+9)}$$

$$(c) \frac{7}{s^2(s+5)}$$

Inverse Laplace Transform

Solution

$$\begin{aligned}(a) \mathcal{L}^{-1}\left\{\frac{1}{(s-1)(s+2)}\right\} &= \mathcal{L}^{-1}\left\{\frac{1}{s-1}\right\} * \mathcal{L}^{-1}\left\{\frac{1}{s+2}\right\} \\ &= e^t * e^{-2t} \\ &= \int_0^t e^{t-v} e^{-2v} dv = \int_0^t e^{t-3v} dv = \left[\frac{e^{t-3v}}{-3} \right]_0^t \\ &= \frac{e^{-2t} - e^t}{-3} = \frac{e^t - e^{-2t}}{3}\end{aligned}$$

Inverse Laplace Transform

Solution

$$\begin{aligned} \text{(b)} \quad \mathcal{L}^{-1}\left\{\frac{12}{s(s^2+9)}\right\} &= 4\mathcal{L}^{-1}\left\{\frac{1}{s} \cdot \frac{3}{s^2+9}\right\} \\ &= 4\mathcal{L}^{-1}\left\{\frac{1}{s}\right\} * \mathcal{L}^{-1}\left\{\frac{3}{s^2+9}\right\} \\ &= 4(1 * \sin 3t) \\ &= 4 \int_0^t 1 \sin 3v \, dv \\ &= 4 \left[\frac{-\cos 3v}{3} \right]_0^t = \frac{4}{3}(1 - \cos 3t) \end{aligned}$$

Inverse Laplace Transform

$$\begin{aligned} \text{(c)} \quad \mathcal{L}^{-1}\left\{\frac{7}{s^2(s+5)}\right\} &= 7\mathcal{L}^{-1}\left\{\frac{1}{s^2} \cdot \frac{1}{s+5}\right\} \\ &= 7\mathcal{L}^{-1}\left\{\frac{1}{s^2}\right\} * \mathcal{L}^{-1}\left\{\frac{1}{s+5}\right\} \\ &= 7t * e^{-5t} = 7 \int_0^t v e^{-5(t-v)} \, dv = 7 \int_0^t v e^{5(v-t)} \, dv \\ &= 7 \left[\frac{v e^{5(v-t)}}{5} \right]_0^t - 7 \int_0^t \frac{e^{5(v-t)}}{5} \, dv \\ &= 7 \left(\frac{t e^0 - 0}{5} \right) - 7 \left[\frac{e^{5(v-t)}}{25} \right]_0^t = \frac{7t}{5} - \frac{7(1 - e^{-5t})}{25} \\ &= \frac{7}{25}(5t + e^{-5t} - 1) \end{aligned}$$

Solution of LDEs Using Laplace Transform

Example: Solve the following Linear DE

$$y'' + 5y' + 6y = 0, \quad y(0) = 2, \quad y'(0) = 3$$

Solution: taking the Laplace transform of Linear DE

$$\mathcal{L}\{y'' + 5y' + 6y\} = \mathcal{L}\{y''\} + 5\mathcal{L}\{y'\} + 6\mathcal{L}\{y\} = \mathcal{L}\{0\} = 0$$

Now find the Laplace transform of derivatives

$$[s^s Y(s) - sy(0) - y'(0)] + 5[sY(s) - y(0)] + 6Y(s) = 0$$

Rearranging the equation

$$(s^2 + 5s + 6)Y(s) - (s + 5)y(0) - y'(0) = 0$$

Substituting in the initial conditions, we obtain

$$(s^2 + 5s + 6)Y(s) - 2(s + 5) - 3 = 0$$

$$Y(s) = \frac{2s + 13}{(s + 3)(s + 2)}$$

Solution of LDEs Using Laplace Transform

Using partial fraction decomposition, $Y(s)$ can be rewritten:

$$\begin{aligned} \frac{2s+13}{(s+3)(s+2)} &= \frac{A}{s+3} + \frac{B}{s+2} \\ 2s+13 &= A(s+2) + B(s+3) \\ 2s+13 &= (A+B)s + (2A+3B) \\ A+B &= 2, \quad 2A+3B = 13 \\ A &= -7, \quad B = 9 \end{aligned}$$

Thus

$$Y(s) = -\frac{7}{(s+3)} + \frac{9}{(s+2)}$$

Now we can find the inverse Laplace transform of $Y(s)$ to get $y(t)$

$$y(t) = -7e^{-3t} + 9e^{-2t}$$

Solution of LDEs Using Laplace Transform

Example: Solve the following Linear DE

$$y'' + y = \sin 2t, \quad y(0) = 2, \quad y'(0) = 1$$

Solution: taking the Laplace transform of Linear DE

$$\mathcal{L}\{y'' + y\} = \mathcal{L}\{y''\} + \mathcal{L}\{y\} = \mathcal{L}\{\sin 2t\}$$

Now find the Laplace transform of derivatives

$$[s^2 Y(s) - sy(0) - y'(0)] + Y(s) = \frac{2}{s^2 + 4}$$

Rearranging the equation

$$(s^2 + 1)Y(s) - sy(0) - y'(0) = \frac{2}{s^2 + 4}$$

Substituting in the initial conditions, we obtain

$$(s^2 + 1)Y(s) - 2s - 1 = \frac{2}{s^2 + 4}$$

$$Y(s) = \frac{2s^3 + s^2 + 8s + 6}{(s^2 + 1)(s^2 + 4)}$$

Solution of LDEs Using Laplace Transform

Using partial fraction, $Y(s)$ can be rewritten:

$$Y(s) = \frac{2s^3 + s^2 + 8s + 6}{(s^2 + 1)(s^2 + 4)} = \frac{As + B}{s^2 + 1} + \frac{Cs + D}{s^2 + 4}$$

Then

$$\begin{aligned} 2s^3 + s^2 + 8s + 6 &= (As + B)(s^2 + 4) + (Cs + D)(s^2 + 1) \\ &= (A + C)s^3 + (B + D)s^2 + (4A + C)s + (4B + D) \end{aligned}$$

Solving, we obtain $A = 2$, $B = 5/3$, $C = 0$, and $D = -2/3$. Thus

$$Y(s) = \frac{2s}{s^2 + 1} + \frac{5/3}{s^2 + 1} - \frac{2/3}{s^2 + 4}$$

Now we can find the inverse Laplace transform of $Y(s)$ to get $y(t)$

$$y(t) = 2 \cos t + \frac{5}{3} \sin t - \frac{1}{3} \sin 2t$$

Solution of LDEs Using Laplace Transform

Example: Solve the following Linear DE

$$y'' + 2y' + 5y = 3, \quad y(0) = 0, \quad y'(0) = 0$$

$$\mathcal{L}\{y''\} + 2\mathcal{L}\{y'\} + 5\mathcal{L}\{y\} = \mathcal{L}\{3\}$$

$$[s^2 Y(s) - sy(0) - y'(0)] + 2[sY(s) - y(0)] + 5Y(s) = \frac{3}{s}$$

$$[s^2 + 2s + 5]Y(s) = \frac{3}{s}$$

$$Y(s) = \frac{3}{s(s + 1 - 2j)(s + 1 + 2j)} = \frac{A}{s} + \frac{B_1}{s + 1 - 2j} + \frac{B_2}{s + 1 + 2j}$$

$$y(t) = A + B_1 e^{-(1-2j)t} + B_2 e^{-(1+2j)t}$$

Where $A = 0.6$, $B_1 = -0.3 + 0.15j = 0.33e^{2.6779j}$, $B_2 = -0.3 - 0.15j = 0.33e^{-2.6779j}$

Initial and Final Value theorem

INITIAL VALUE THEOREM

Assume that $f(t)$ has Laplace transform.

Then,

$$\lim_{t \rightarrow 0} f(t) = \lim_{s \rightarrow \infty} sF(s)$$

FINAL VALUE THEOREM

Assume that $f(t)$ has Laplace transform and that $\lim_{n \rightarrow \infty} f(t)$ exist.

Then,

$$\lim_{t \rightarrow \infty} f(t) = \lim_{s \rightarrow 0} sF(s)$$

Note: $\lim_{n \rightarrow \infty} f(t)$ will exist if $F(s)$ has poles with negative real part and at most a single pole at $s = 0$.

Initial and Final Value theorem

Example: Given

$$F(s) = \frac{10(s+1)}{s(s^2+2s+2)}$$

Determine the initial and final values for $f(t)$.

$$\lim_{t \rightarrow 0} f(t) = \lim_{s \rightarrow \infty} sF(s) = \lim_{s \rightarrow \infty} \frac{10(s+1)}{s^2+2s+2} = 0$$

$F(s)$ has one pole at $s=0$ and the others have negative real part. The final value theorem can be applied.

$$\lim_{t \rightarrow \infty} f(t) = \lim_{s \rightarrow 0} sF(s) = \lim_{s \rightarrow 0} \frac{10(s+1)}{s^2+2s+2} = 5$$

Note: Computing the inverse one can get

$$f(t) = 5 + 5\sqrt{2}e^{-t} \cos\left(t - \frac{3\pi}{4}\right)$$

Initial and Final Value theorem

Example: Investigate the application of initial and final value theorem to the Laplace transform function

$$F(s) = \frac{1}{(s+2)(s-3)}$$

Solution:

For the initial value theorem:

$$\lim_{s \rightarrow \infty} sF(s) = \lim_{s \rightarrow \infty} \frac{s}{(s+2)(s-3)} = 0$$

$$f(t) = \frac{1}{5}(e^{3t} - e^{-2t})$$

$$\lim_{t \rightarrow 0} f(t) = \lim_{t \rightarrow 0} \frac{1}{5}(e^0 - e^0) = 0$$

For the final value theorem:

$$\lim_{s \rightarrow 0} sF(s) = \lim_{s \rightarrow 0} \frac{s}{(s+2)(s-3)} = 0$$

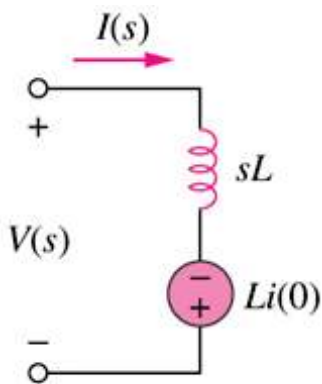
$$\lim_{t \rightarrow \infty} f(t) = \lim_{t \rightarrow \infty} \frac{1}{5}(e^\infty - e^{-\infty}) = \infty$$

∴ the system is not stable (is not steady-state gain)

Circuit Application

1. RLC circuit with initial condition
 2. Transfer functions
 3. Block Diagram
-

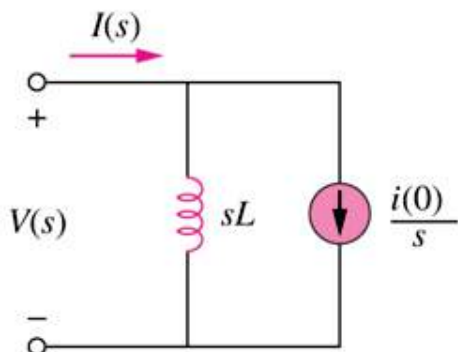
RLC circuit



$$v_L(t) = L \frac{di_L(t)}{dt}$$

Taking the Laplace transform

$$V_L(s) = (sL)I_L(s) - Li_L(0)$$

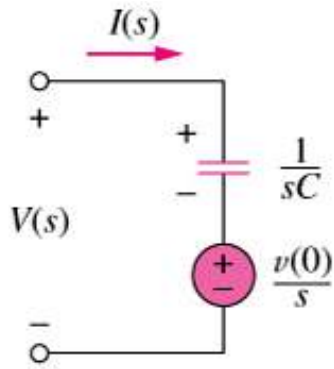


$$i_L(t) = \frac{1}{L} \int_0^t v_L(t) dt + i_L(0)$$

Taking the Laplace transform

$$I_L(s) = \frac{V_L(s)}{sL} + \frac{i_L(0)}{s}$$

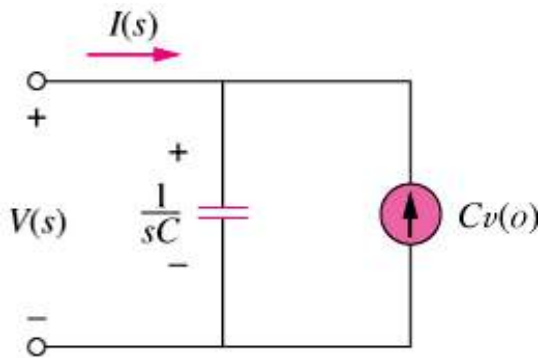
RLC circuit



$$v_c(t) = \frac{1}{C} \int_0^t i_c(t) dt + v_c(0)$$

Taking the Laplace transform

$$V_c(s) = \frac{1}{sC} I_c(s) + \frac{v_c(0)}{s}$$



$$i_c(t) = C \frac{dv_c(t)}{dt}$$

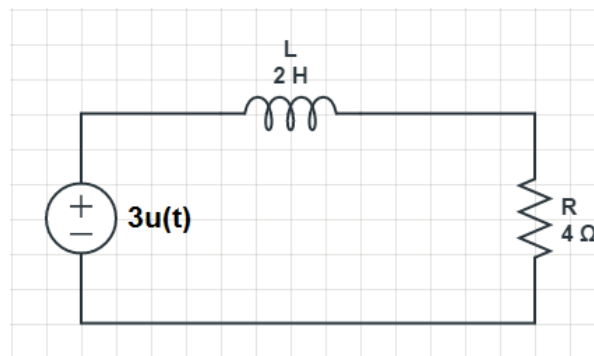
Taking the Laplace transform

$$I_c(s) = \frac{V_c(s)}{1/sC} - Cv_c(0)$$

RLC circuit

Example:

In the RL-Series circuit given that $i(0) = 5$ Amp, find $i(t)$



Using KVL

$$L \frac{di}{dt} + Ri = 3u(t) \quad \text{Taking Laplace transform}$$

$$L[sI(s) - i(0)] + RI(s) = \frac{3}{s}$$

RLC circuit

$$2[sI(s) - 5] + 4I(s) = \frac{3}{s}$$

$$I(s)[2s + 4] = \frac{3}{s} + 10$$

$$I(s)[s + 2] = \frac{1.5}{s} + 5 = \frac{5s + 3/2}{s}$$

$$I(s) = \frac{5s + 3/2}{s(s + 2)} = \frac{A}{s} + \frac{B}{s + 2} = \frac{A(s + 2) + Bs}{s(s + 2)}$$

Equating coefficients

$$\frac{3}{2} = 2A \quad \Rightarrow \quad A = \frac{3}{4}$$

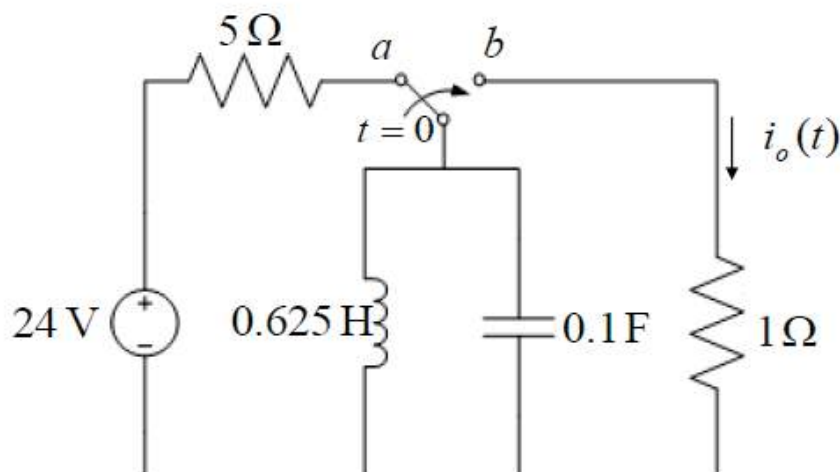
$$5 = A + B \quad \Rightarrow \quad B = \frac{17}{4}$$

$$I(s) = \frac{5s + 3/2}{s(s + 2)} = \frac{3}{4s} + \frac{17}{4(s + 2)} \quad \Rightarrow \quad \mathcal{L}^{-1}\{I(s)\} = i(t) = \frac{3}{4}u(t) + \frac{17}{4}e^{-2t}u(t)$$

RLC circuit

Example:

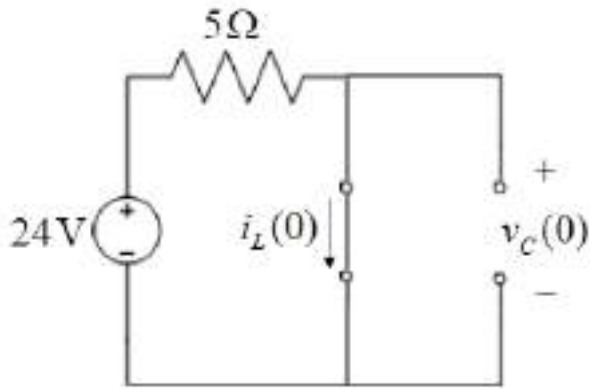
The switch in the following circuit moves from position *a* to position *b* at $t = 0$ second. Compute $i_o(t)$ for $t > 0$.



RLC circuit

Solution:

The i.c. (initial condition) are not given directly. Hence, at first we need to find the i.c. by analyzing the circuit when $t \leq 0$:

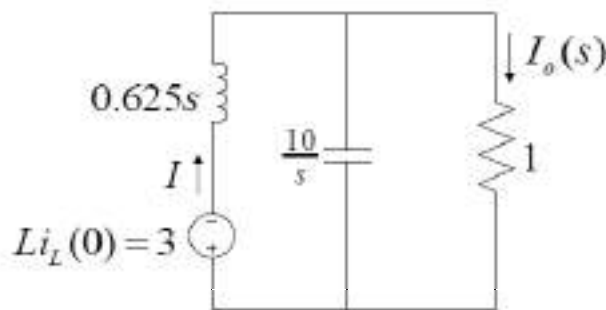


$$i_L(0) = \frac{24}{5} = 4.8A$$

$$v_L(0) = 0V$$

RLC circuit

Then, we can analyze the circuit for $t > 0$ by considering the i.c.



$$I = \frac{-3}{0.625s + \left(\frac{10}{s} \parallel 1\right)} = \frac{-3}{0.625s + \left(\frac{\frac{10}{s}}{\frac{10}{s} + 1}\right)} = \frac{-3}{0.625s + \left(\frac{10}{s+10}\right)} = \frac{-3}{\frac{0.625s^2 + 6.25s + 10}{s+10}}$$

$$I = \frac{-3(s+10)}{0.625s^2 + 6.25s + 10}$$

RLC circuit

Using current divider rule, we find that

$$I_0 = \frac{\frac{10}{s}}{\frac{10}{s} + 1} I = \frac{10}{(10 + s)} \frac{-3(s + 10)}{0.625s^2 + 6.25s + 10} = \frac{-30}{0.625s^2 + 6.25s + 10}$$

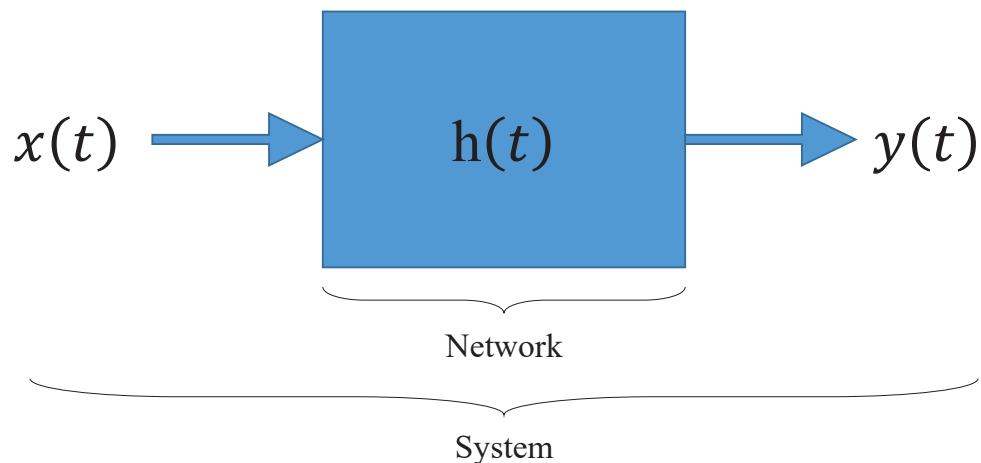
$$I_0 = \frac{-30}{0.625s^2 + 6.25s + 10} = \frac{-30}{0.625(s^2 + 10s + 16)} = \frac{-48}{s^2 + 10s + 16}$$

Using partial fraction, we have

$$I_0(s) = \frac{-48}{(s + 8)(s + 2)} = \frac{8}{s + 8} - \frac{8}{s + 2}$$

$$i_0(t) = 8(e^{-8t} - e^{-2t})u(t) \text{ A}$$

Transfer Function



In time domain, $y(t) = h(t) * x(t)$

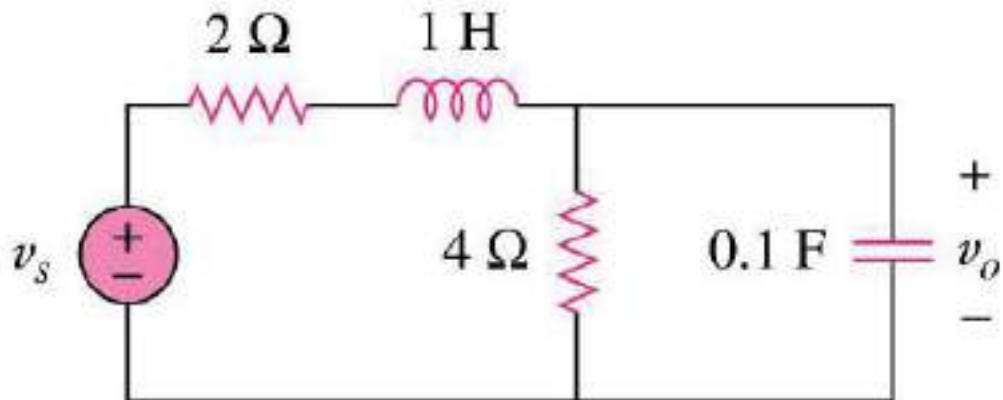
In s-domain, $Y(s) = H(s)X(s)$

\therefore Transfer Function, $H(S) = \frac{Y(s)}{X(s)}$

Transfer Function

Example:

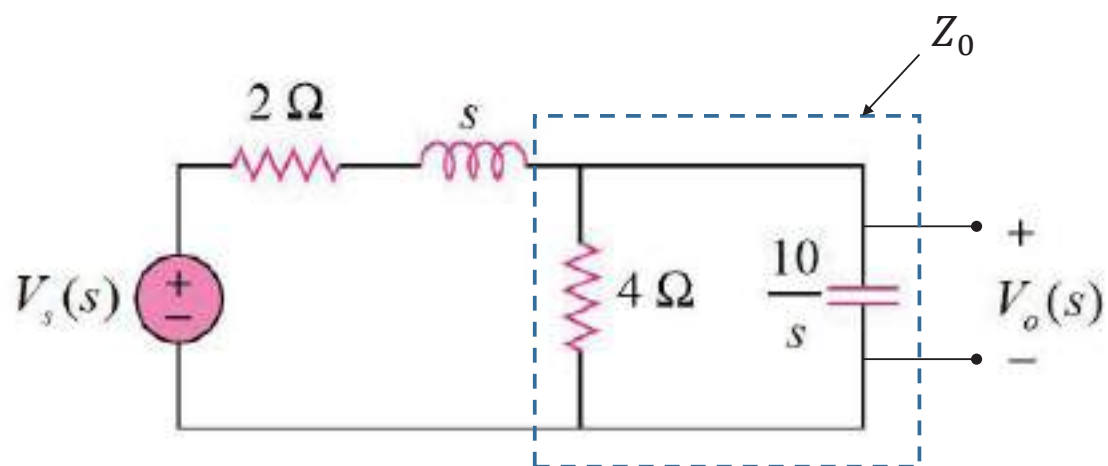
For the following circuit, find $H(s) = V_o(s)/V_i(s)$. Assume zero initial conditions.



Transfer Function

Solution:

Transform the circuit into s-domain with zero i.c.:



Transfer Function

$$Z_0 = 4 \parallel \frac{10}{s} = \frac{\frac{40}{s}}{4 + \frac{10}{s}} = \frac{40}{4s + 10} = \frac{20}{2s + 5}$$

Using voltage divider

$$V_0 = \frac{\frac{20}{2s + 5}}{\frac{20}{2s + 5} + s + 2} V_s = \frac{20}{20 + (2s + 5)(s + 2)} V_s$$

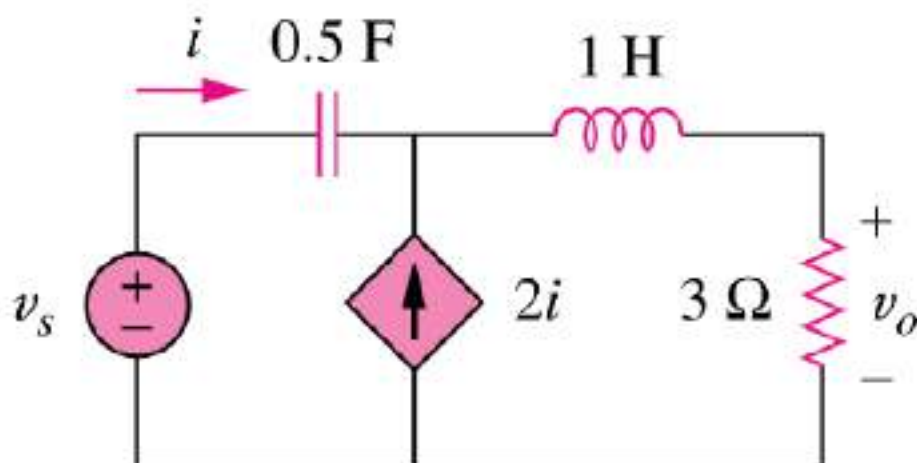
$$V_0 = \frac{20}{2s^2 + 9s + 30} V_s$$

$$H(s) = \frac{V_0(s)}{V_s(s)} = \frac{20}{2s^2 + 9s + 30}$$

Transfer Function

Example:

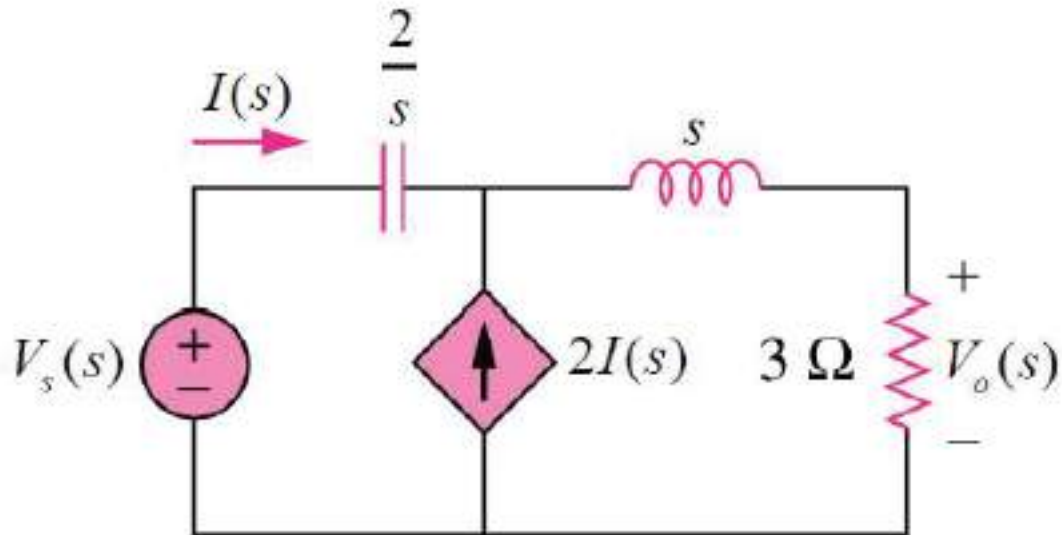
Obtain the transfer function $H(s) = V_0(s)/V_i(s)$, for the following circuit.



Transfer Function

Solution:

Transform the circuit into s-domain (We can assume zero i.c. unless stated in the question)



Transfer Function

We found that

$$V_o = 3(I + 2I) = 9I$$

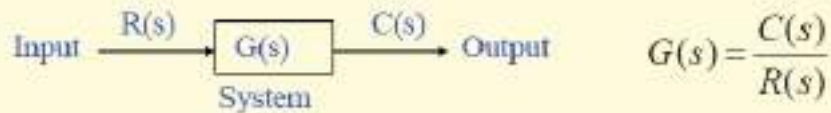
$$V_s = \frac{2}{s}I + (s + 3)3I = \left(\frac{2}{s} + 3s + 9 \right) I$$

$$\therefore H(s) = \frac{V_o(s)}{V_s(s)} = \frac{9}{\frac{2}{s} + 3s + 9} = \frac{9s}{3s^2 + 9s + 2}$$

Block Diagram

A block diagram is a graphical tool that can help us to visualize the model of a system and evaluate the mathematical relationships between their elements, using their transfer functions.

The Transfer Function Block

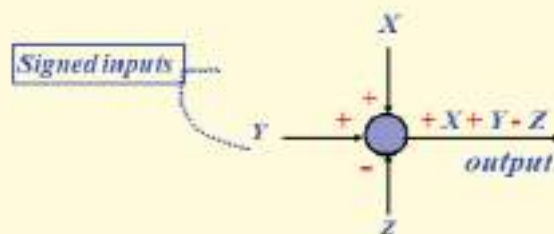


The transfer function $G(s)$ is

- defined only for a linear time-invariant system and not for nonlinear systems.
- Is a **property** of the system and is **independent of the input** to the system.
- Commutative $G_1 G_2 = G_2 G_1$
- Associative $G_1 + G_2 = G_2 + G_1$

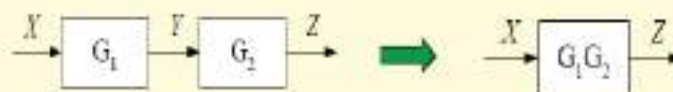
Block Diagram Elements

The Summing Point

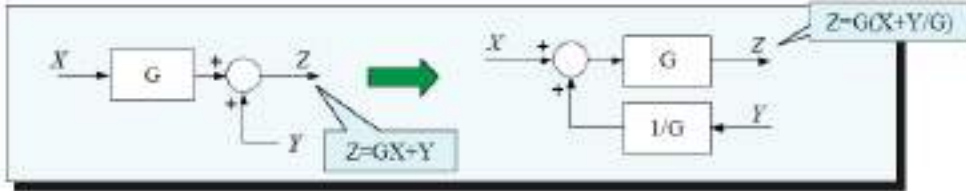
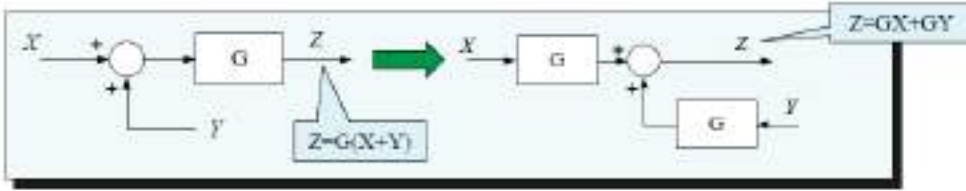
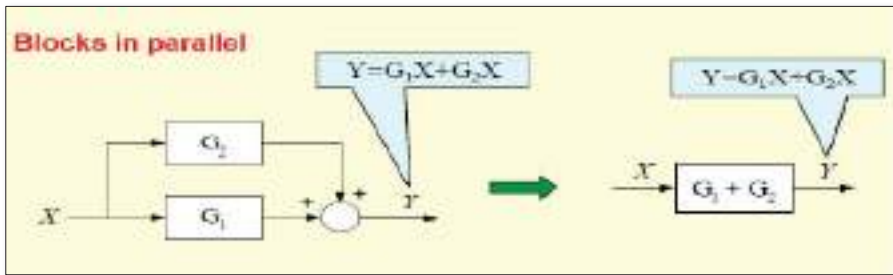


- Any number of inputs. Only **one** output

Blocks in series or cascaded blocks

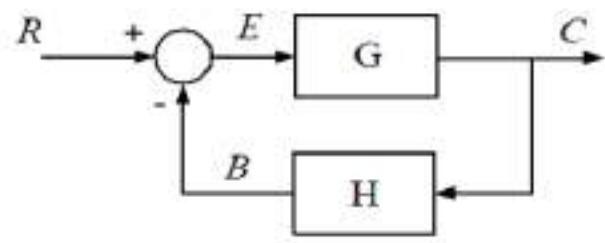


- When blocks are connected in series, there must be **no loading effect**.



Block Diagram

Closed-loop Feedback System



- R is called the reference input
- C is the output or controlled variable
- B is the feedback
- $E = (R - B)$ is the error
- $G = \frac{C}{E}$ is called the feed-forward transfer function
- $GH = \frac{B}{E}$ is called the open-loop transfer function

Block Diagram

Overall transfer function of closed-loop feedback system

$$E(s) = R(s) - B(s)$$

$$\frac{C(s)}{G(s)} = R(s) - B(s)$$

$$\frac{C(s)}{G(s)} = R(s) - C(s)H(s)$$

$$\frac{C(s)}{G(s)} + C(s)H(s) = R(s)$$

$$C(s) \left[\frac{1}{G(s)} + H(s) \right] = R(s)$$

$$C(s) \left[\frac{1 + G(s)H(s)}{G(s)} \right] = R(s)$$

$$\frac{C(s)}{R(s)} = \left[\frac{G(s)}{1 + G(s)H(s)} \right]$$

Block Diagram

- **Eliminating a negative feedback loop**

The overall transfer function for a negative feedback loop is given by

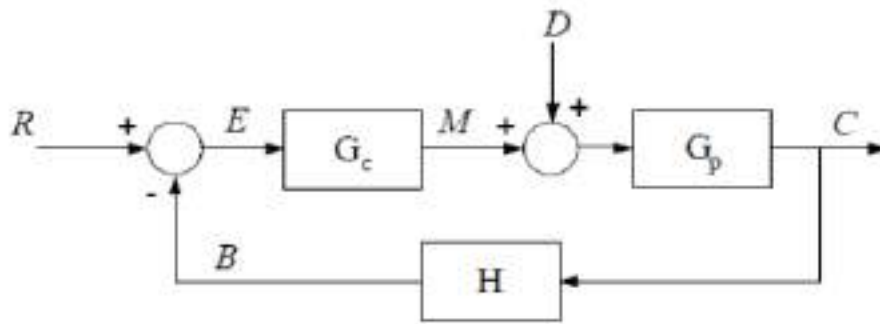
$$\frac{C(s)}{R(s)} = \left[\frac{G(s)}{1 + G(s)H(s)} \right]$$

- **Eliminating a positive feedback loop**

The overall transfer function for a positive feedback loop is given by

$$\frac{C(s)}{R(s)} = \left[\frac{G(s)}{1 - G(s)H(s)} \right]$$

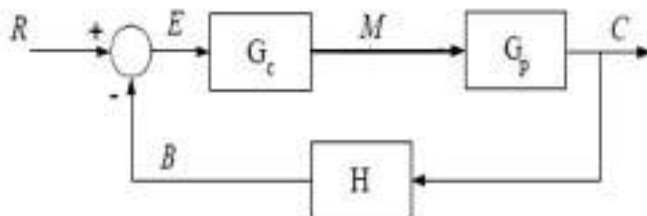
Block Diagram



- G_e is the controller transfer function
- G_p is the plant transfer function
- M is the manipulated variable
- D is the external disturbance
- $G_e G_p = \frac{C}{E}$ is the feed-forward transfer function
- $G_e G_p H = \frac{B}{E}$ is the open-loop transfer function

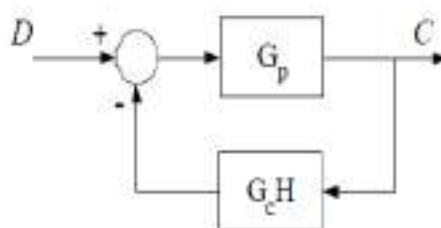
Block Diagram

Assuming $D = 0$, we can re-draw



$$\frac{C}{R} = \frac{G}{1+GH} = \frac{G_c G_p}{1+G_c G_p H}$$

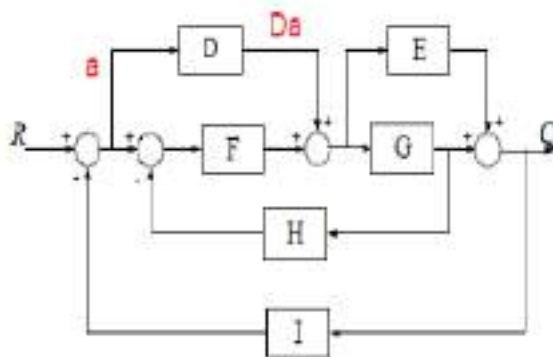
Assuming $R = 0$, we can re-draw



$$\frac{C}{D} = \frac{G}{1+GH} = \frac{G_p}{1+G_p G_c H}$$

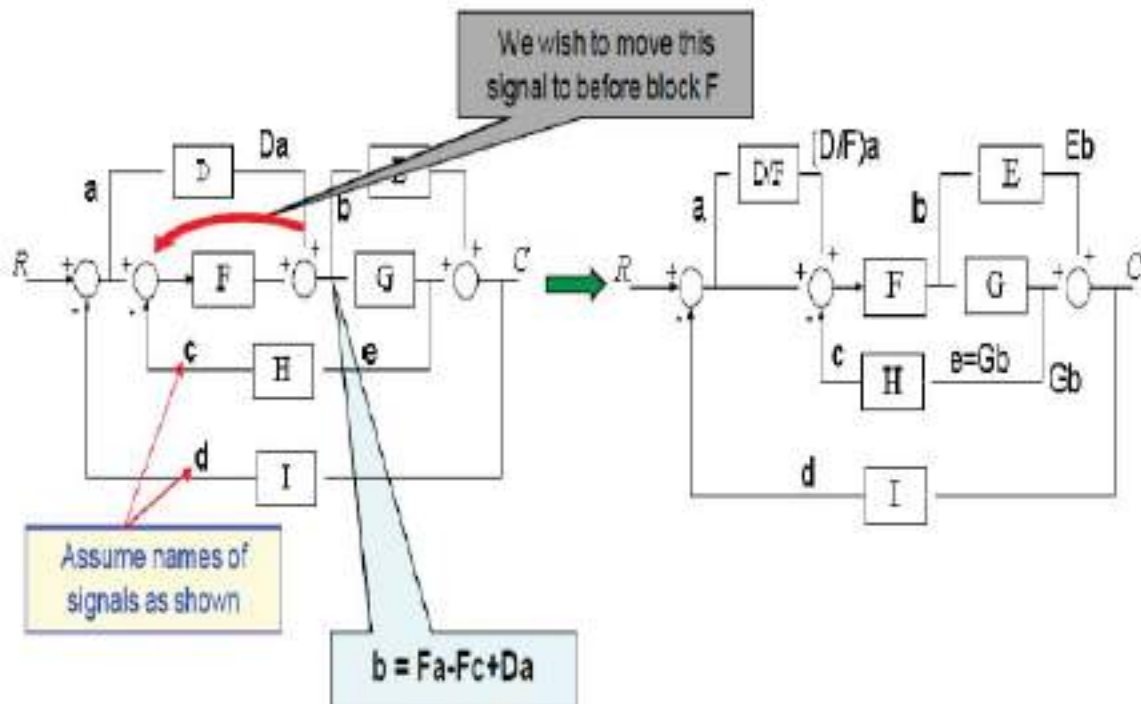
Block Diagram

Example: Determine $C(s)/R(s)$

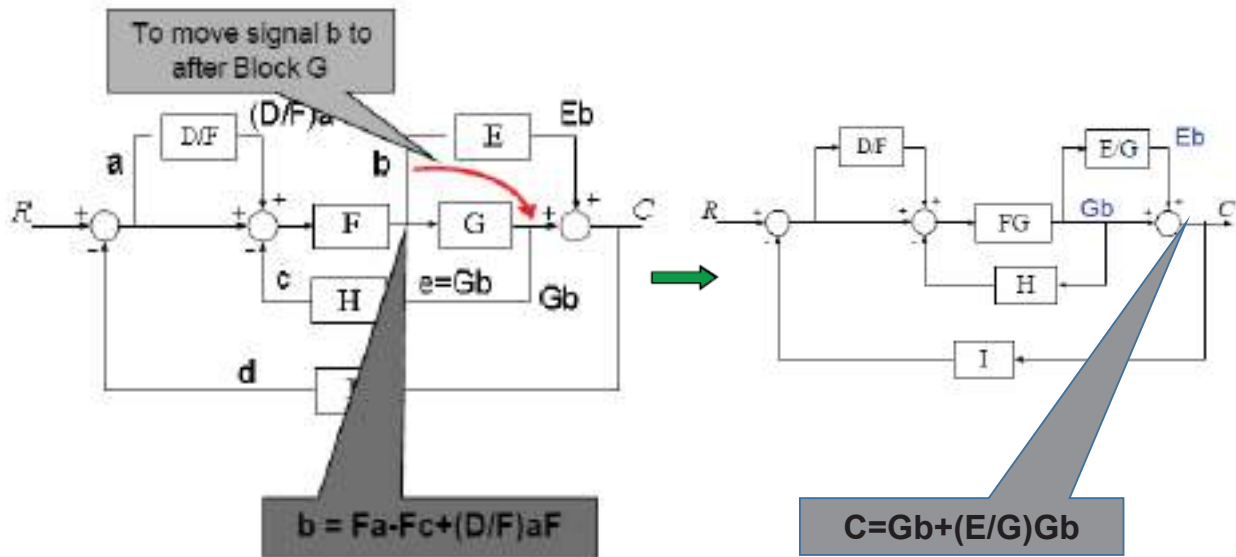


When manipulating blocks, must ensure $C(s)$ does not change, so that $C(s)/R(s)$ remains same.

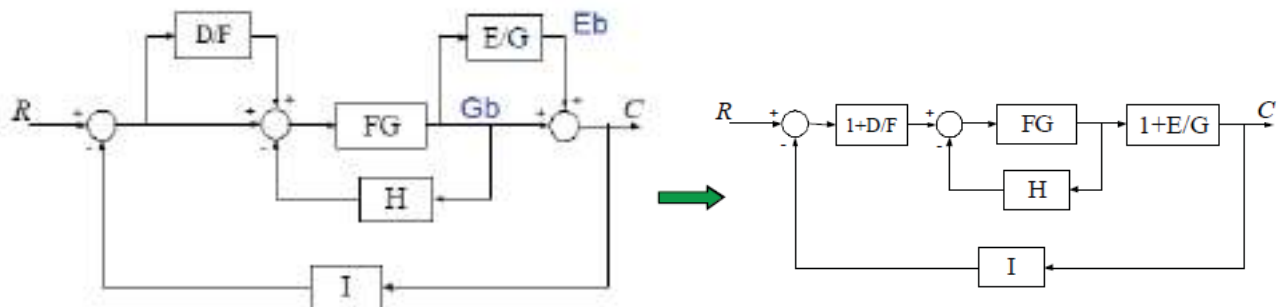
Block Diagram



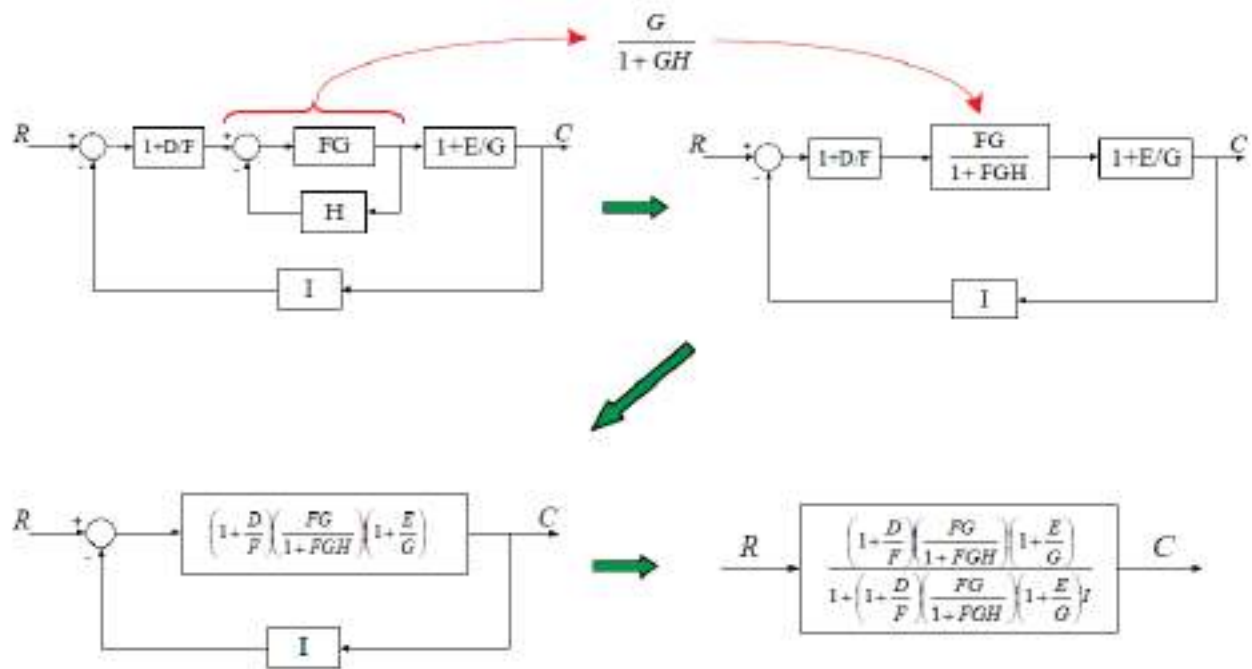
Block Diagram



Block Diagram

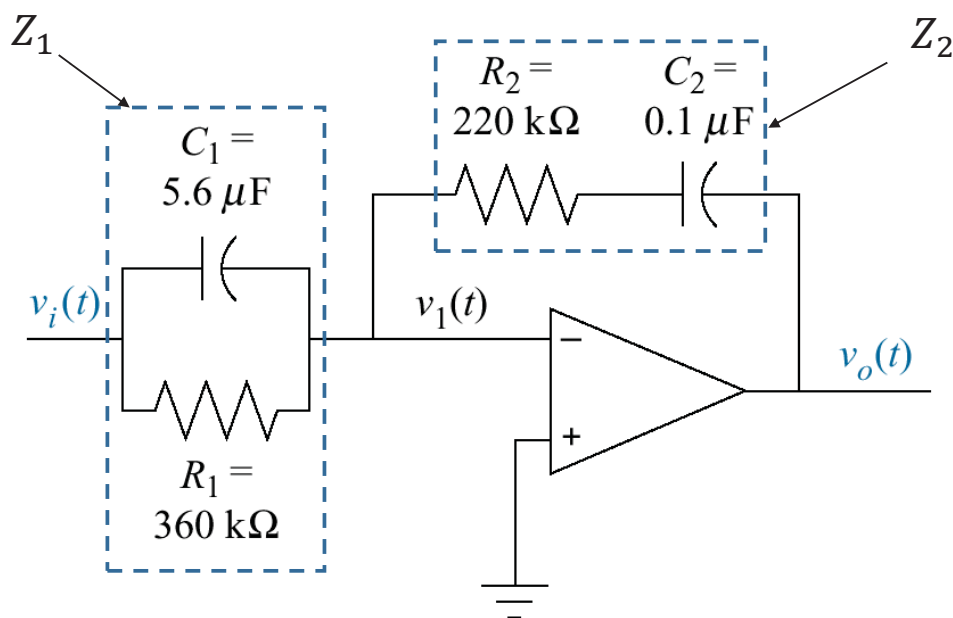


Block Diagram



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Inverting operational amplifier circuit:



Block Diagram

$$Z_1(s) = \frac{1}{C_1 s + \frac{1}{R_1}} = \frac{1}{5.6 * 10^{-6} s + \frac{1}{360 * 10^3}}$$
$$= \frac{360 * 10^3}{2.016s + 1}$$

$$Z_2(s) = R_2 + \frac{1}{C_2 s} = 220 * 10^3 + \frac{10^7}{s} = \frac{220 * 10^3 s + 10^7}{s}$$

$$\frac{V_o(s)}{V_i(s)} = -\frac{Z_2(s)}{Z_1(s)} = -\frac{\frac{220 * 10^3 s + 10^7}{s}}{\frac{360 * 10^3}{2.016s + 1}}$$

$$\frac{V_o(s)}{V_i(s)} = -\frac{(220 * 10^3 s + 10^7)(2.016s + 1)}{360 * 10^3 s} = -1.232 \frac{s^2 + 45.95s + 22.55}{s}$$