

# Maxwell's Equations

## Lecture 6

## Introduction

stationary charges → electrostatic fields  
steady currents → magnetostatic fields  
time-varying currents → electromagnetic fields (or waves)

## Faraday's Law

- Faraday discovered that the induced emf,  $V_{\text{emf}}$  (in volts), in any closed circuit is equal to the time rate of change of the magnetic flux linkage by the circuit.

$$V_{\text{emf}} = -N \frac{d\Phi}{dt}$$

- where  $N$  is the number of turns in the circuit and  $\Phi$  is the flux through each turn. The negative sign shows that the induced voltage acts in such a way as to oppose the flux producing it. This is known as *Lenz's law*.

## Faraday's Law ( Con,d)

$$V_{\text{emf}} = \oint_L \mathbf{E} \cdot d\mathbf{l} = -\frac{d}{dt} \int_S \mathbf{B} \cdot d\mathbf{S}$$

$$V_{\text{emf}} = \oint_L \mathbf{E} \cdot d\mathbf{l} = - \int_S \frac{\partial \mathbf{B}}{\partial t} \cdot d\mathbf{S}$$

By applying Stokes's theorem to the middle term in eq.

$$\int_S (\nabla \times \mathbf{E}) \cdot d\mathbf{S} = - \int_S \frac{\partial \mathbf{B}}{\partial t} \cdot d\mathbf{S}$$

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t} \quad \text{It shows that the time varying E field is not conservative } (\nabla \times \mathbf{E} \neq 0)$$

## DISPLACEMENT CURRENT

For static EM fields, we recall that

$$\nabla \times \mathbf{H} = \mathbf{J}$$

But the divergence of the curl of any vector field is identically zero  
Hence,

$$\nabla \cdot (\nabla \times \mathbf{H}) = 0 = \nabla \cdot \mathbf{J}$$

The continuity of current however, requires that

$$\nabla \cdot \mathbf{J} = -\frac{\partial \rho_v}{\partial t} \neq 0$$

$$\nabla \times \mathbf{H} = \mathbf{J} + \mathbf{J}_d$$

## DISPLACEMENT CURRENT

where  $\mathbf{J}_d$  is to be determined and defined. Again, the divergence of the curl of any vector is zero. Hence:

$$\nabla \cdot (\nabla \times \mathbf{H}) = 0 = \nabla \cdot \mathbf{J} + \nabla \cdot \mathbf{J}_d$$

$$\nabla \cdot \mathbf{J}_d = -\nabla \cdot \mathbf{J} = \frac{\partial \rho_v}{\partial t} = \frac{\partial}{\partial t} (\nabla \cdot \mathbf{D}) = \nabla \cdot \frac{\partial \mathbf{D}}{\partial t}$$

$$\mathbf{J}_d = \frac{\partial \mathbf{D}}{\partial t}$$

$$\nabla \times \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t}$$

## DISPLACEMENT CURRENT

This is Maxwell's equation (based on Ampere's circuit law) for a time-varying field. The term  $\mathbf{J}_d = \partial \mathbf{D} / \partial t$  is known as *displacement current density* and  $\mathbf{J}$  is the conduction current density ( $\mathbf{J} = \sigma \mathbf{E}$ )

## Maxwell's Equations

Generalized Forms of Maxwell's Equations

Differential Form	Integral Form	Remarks
$\nabla \cdot \mathbf{D} = \rho_v$	$\oint_S \mathbf{D} \cdot d\mathbf{S} = \int_v \rho_v dv$	Gauss's law
$\nabla \cdot \mathbf{B} = 0$	$\oint_S \mathbf{B} \cdot d\mathbf{S} = 0$	Nonexistence of isolated magnetic charge*
$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$	$\oint_L \mathbf{E} \cdot d\mathbf{l} = -\frac{\partial}{\partial t} \int_S \mathbf{B} \cdot d\mathbf{S}$	Faraday's law
$\nabla \times \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t}$	$\oint_L \mathbf{H} \cdot d\mathbf{l} = \int_S \left( \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t} \right) \cdot d\mathbf{S}$	Ampere's circuit law

\*This is also referred to as Gauss's law for magnetic fields.

## ELECTROMAGNETIC WAVE PROPAGATION

- In general, **waves are means of transporting energy or information.**
- All forms of EM energy share three fundamental characteristics:
- they all travel at high velocity;
- in traveling, they assume the properties of waves;
- and they radiate outward from a source

## Solution of Maxwell's Equations

- goal is to solve Maxwell's equations and derive EM wave motion in the following media:
1. Free space ( $\sigma = 0, \epsilon = \epsilon_0, \mu = \mu_0$ )
  2. Lossless dielectrics ( $\sigma = 0, \epsilon = \epsilon_r \epsilon_0, \mu = \mu_r \mu_0$ , or  $\sigma \ll \omega \epsilon$ )
  3. Lossy dielectrics ( $\sigma \neq 0, \epsilon = \epsilon_r \epsilon_0, \mu = \mu_r \mu_0$ )
  4. Good conductors ( $\sigma \approx \infty, \epsilon = \epsilon_0, \mu = \mu_r \mu_0$ , or  $\sigma \gg \omega \epsilon$ )

where  $\omega$  is the angular frequency of the wave

## Solution of Maxwell's Equations

Consider a linear, isotropic, homogeneous, lossy dielectric medium that is charge free ( $\rho_v = 0$ ). Assuming and suppressing the time factor  $e^{j\omega t}$ , Maxwell's equations become

$$\nabla \cdot \mathbf{E}_s = 0$$

$$\nabla \cdot \mathbf{H}_s = 0$$

$$\nabla \times \mathbf{E}_s = -j\omega\mu\mathbf{H}_s$$

$$\nabla \times \mathbf{H}_s = (\sigma + j\omega\epsilon)\mathbf{E}_s$$

Taking the curl of both sides of  $\nabla \times \mathbf{E}_s = -j\omega\mu\mathbf{H}_s$

$$\nabla \times \nabla \times \mathbf{E}_s = -j\omega\mu \nabla \times \mathbf{H}_s$$

## Solution of Maxwell's Equations

Applying the vector identity

$$\nabla \times \nabla \times \mathbf{A} = \nabla(\nabla \cdot \mathbf{A}) - \nabla^2 \mathbf{A}$$

$$\nabla(\nabla \cdot \mathbf{E}_s) - \nabla^2 \mathbf{E}_s = -j\omega\mu(\sigma + j\omega\epsilon)\mathbf{E}_s$$

or

$$\boxed{\nabla^2 \mathbf{E}_s - \gamma^2 \mathbf{E}_s = 0} \quad \text{wave equation.}$$

where

$$\gamma^2 = j\omega\mu(\sigma + j\omega\epsilon)$$

By a similar procedure  $\nabla^2 \mathbf{H}_s - \gamma^2 \mathbf{H}_s = 0$  *wave equation.*

$\gamma$  is called the *propagation constant* (in per meter) of the medium:

$$\gamma = \alpha + j\beta$$

$$-\text{Re } \gamma^2 = \beta^2 - \alpha^2 = \omega^2 \mu \epsilon$$

$$|\gamma^2| = \beta^2 + \alpha^2 = \omega \mu \sqrt{\sigma^2 + \omega^2 \epsilon^2}$$

$$\alpha = \omega \sqrt{\frac{\mu \epsilon}{2} \left[ \sqrt{1 + \left[ \frac{\sigma}{\omega \epsilon} \right]^2} - 1 \right]} \quad \alpha \text{ is known as the } \textit{attenuation constant}$$

$$\beta = \omega \sqrt{\frac{\mu \epsilon}{2} \left[ \sqrt{1 + \left[ \frac{\sigma}{\omega \epsilon} \right]^2} + 1 \right]}$$

$\beta$  is phase shift per length and is called the *phase constant* or *wave number*.

assume that the wave propagates along  $+\mathbf{a}_z$  and that

$\mathbf{E}_s$  has only an  $x$ -component, then

$$\mathbf{E}_s = E_{xs}(z) \mathbf{a}_x$$

$$(\nabla^2 - \gamma^2) E_{xs}(z)$$

$$\underbrace{\frac{\partial^2 E_{xs}(z)}{\partial x^2}}_0 + \underbrace{\frac{\partial^2 E_{xs}(z)}{\partial y^2}}_0 + \frac{\partial^2 E_{xs}(z)}{\partial z^2} - \gamma^2 E_{xs}(z) = 0$$

$$\left[ \frac{d^2}{dz^2} - \gamma^2 \right] E_{xs}(z) = 0$$

$$E_{xs}(z) = E_o e^{-\gamma z} + E'_o e^{\gamma z}$$

where  $E_o$  and  $E'_o$  are constants. The fact that the field must be finite at infinity requires that

$$E'_o = 0$$

$$\mathbf{E}(z, t) = \text{Re} [E_{xs}(z) e^{j\omega t} \mathbf{a}_x] = \text{Re} (E_o e^{-\alpha z} e^{j(\omega t - \beta z)} \mathbf{a}_x)$$

$$\mathbf{E}(z, t) = E_o e^{-\alpha z} \cos(\omega t - \beta z) \mathbf{a}_x$$

$$\mathbf{H}(z, t) = \text{Re} (H_o e^{-\alpha z} e^{j(\omega t - \beta z)} \mathbf{a}_y)$$

$$H_o = \frac{E_o}{\eta}$$

$$\eta = \sqrt{\frac{j\omega\mu}{\sigma + j\omega\epsilon}} = |\eta| \angle \theta_\eta = |\eta| e^{j\theta_\eta}$$

$\eta$  is a complex quantity known as the *intrinsic impedance* (in ohms) of the medium.

the wave velocity  $u$  and wavelength  $\lambda$  are, respectively, given by

$$u = \frac{\omega}{\beta}, \quad \lambda = \frac{2\pi}{\beta}$$



the ratio of the magnitude of the conduction current density  $\mathbf{J}$  to that of the displacement current density  $\mathbf{J}_d$  in a lossy medium

$$\frac{|\mathbf{J}_s|}{|\mathbf{J}_{ds}|} = \frac{|\sigma \mathbf{E}_s|}{|j\omega \epsilon \mathbf{E}_s|} = \frac{\sigma}{\omega \epsilon} = \tan \theta \quad \tan \theta = \frac{\sigma}{\omega \epsilon}$$

$\theta$  is known as the *loss tangent* and  $\theta$  is the *loss angle* of the medium

$$\begin{aligned} \nabla \times \mathbf{H}_s &= (\sigma + j\omega \epsilon) \mathbf{E}_s = j\omega \epsilon \left[ 1 - \frac{j\sigma}{\omega \epsilon} \right] \mathbf{E}_s \\ &= j\omega \epsilon_c \mathbf{E}_s \end{aligned}$$

$$\epsilon_c = \epsilon \left[ 1 - j \frac{\sigma}{\omega \epsilon} \right]$$

$$\epsilon_c = \epsilon' - j\epsilon''$$

and  $\epsilon' = \epsilon$ ,  $\epsilon'' = \sigma/\omega$ ;  $\epsilon_c$  is called the *complex permittivity* of the medium. We observe that the ratio of  $\epsilon''$  to  $\epsilon'$  is the loss tangent of the medium; that is,

$$\tan \theta = \frac{\epsilon''}{\epsilon'} = \frac{\sigma}{\omega \epsilon}$$

## PLANE WAVES IN LOSSLESS DIELECTRICS

In a lossless dielectric,  $\sigma \ll \omega\epsilon$

$$\sigma \approx 0, \quad \epsilon = \epsilon_0\epsilon_r, \quad \mu = \mu_0\mu_r$$

$$\alpha = 0, \quad \beta = \omega\sqrt{\mu\epsilon}$$

$$u = \frac{\omega}{\beta} = \frac{1}{\sqrt{\mu\epsilon}}, \quad \lambda = \frac{2\pi}{\beta} \quad \eta = \sqrt{\frac{\mu}{\epsilon}} \angle 0^\circ$$

and thus **E** and **H** are in time phase with each other.

## PLANE WAVES IN FREE SPACE

$$\sigma = 0, \quad \epsilon = \epsilon_0, \quad \mu = \mu_0$$

$$\alpha = 0, \quad \beta = \omega\sqrt{\mu_0\epsilon_0} = \frac{\omega}{c}$$

$$u = \frac{1}{\sqrt{\mu_0\epsilon_0}} = c, \quad \lambda = \frac{2\pi}{\beta}$$

$$\eta_0 = \sqrt{\frac{\mu_0}{\epsilon_0}} = 120\pi \approx 377 \Omega$$

$$\mathbf{E} = E_o \cos(\omega t - \beta z) \mathbf{a}_x$$

$$\mathbf{H} = H_o \cos(\omega t - \beta z) \mathbf{a}_y = \frac{E_o}{\eta_o} \cos(\omega t - \beta z) \mathbf{a}_y$$

## PLANE WAVES IN GOOD CONDUCTORS

$$\sigma \gg \omega \epsilon \text{ so that } \sigma/\omega \epsilon \rightarrow \infty$$

$$\sigma \approx \infty, \quad \epsilon = \epsilon_o, \quad \mu = \mu_o \mu_r$$

$$\alpha = \beta = \sqrt{\frac{\omega \mu \sigma}{2}} = \sqrt{\pi f \mu \sigma}$$

$$u = \frac{\omega}{\beta} = \sqrt{\frac{2\omega}{\mu \sigma}}, \quad \lambda = \frac{2\pi}{\beta}$$

$$\eta = \sqrt{\frac{\omega \mu}{\sigma}} \angle 45^\circ$$

$$\mathbf{E} = E_0 e^{-\alpha z} \cos(\omega t - \beta z) \mathbf{a}_x$$

$$\mathbf{H} = \frac{E_0}{\sqrt{\frac{\omega\mu}{\sigma}}} e^{-\alpha z} \cos(\omega t - \beta z - 45^\circ) \mathbf{a}_y$$

$$E_0 e^{-\alpha\delta} = E_0 e^{-1}$$

$$\delta = \frac{1}{\alpha}$$

The distance  $\delta$  through which the wave amplitude decreases by a factor  $e^{-1}$  (about 37%) is called *skin depth* or *penetration depth* of the medium

- The **skin depth** is a measure of the depth to which an EM wave can penetrate the medium.

- The net electric flux through any closed (Gaussian) surface is proportional to the net charge inside the surface.
- The net Magnetic flux through any closed (Gaussian) surface is equal to zero, means there is no Magnetism Monopole.

- The line integral of the electric field vector around any closed path equals the rate of change in the magnetic flux through any surface bounded by that path.
- The circulation of the magnetic field vector around any amperian loop is proportional to the sum of the total conduction and displacement current through any surface bounded by the path.