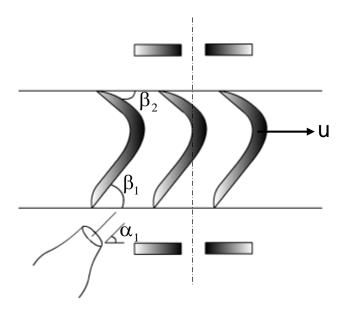
5. Force on Series of Blades (Blade Cascade)

The flow relative to the blade enters and leaves tangent to the profile of the blade.

Constructing velocity triangles at inlet & outlet and applying momentum equation the force components in the x & y directions on the blade system can be obtained.

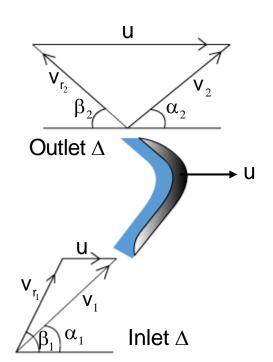


X - direction

$$-F_{x} = \rho Q(V_{2x} - V_{1x})$$

$$Q = A_{1}V_{1} \qquad (a Series of blades)$$

$$-F_{x} = \rho A_{1}V_{1}(V_{2} \cos \alpha_{2} - V_{1} \cos \alpha_{1})$$



Y - direction

$$F_{y} = \rho A_1 V_1 (V_2 \sin \alpha_2 - V_1 \sin \alpha_1)$$

Power developed

$$P = F_x * u$$

The power developed can also be calculate from.

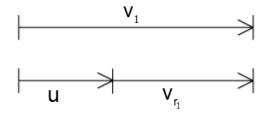
$$P = \rho g Q(\frac{V_1^2 - V_2^2}{2g})$$

6. The Pelton Wheel (Impulse Turbine)

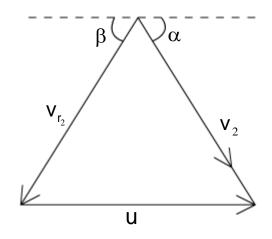
The velocity of the bucket

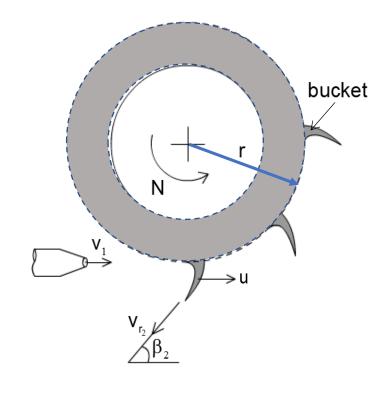
$$u=\omega.r=\frac{2\pi N}{60}.r$$

Velocity triangle at inlet



Velocity triangle at outlet





X - direction

$$-F_X = \rho Q(V_{2x} - V_{1x})$$
$$-F_X = \rho A_1 V_1 (V_2 \cos \alpha - V_1)$$

or

$$F_X = \rho A_1 V_1 (V_1 - V_2 \cos \alpha)$$

From the velocity diagram at outlet.

$$V_2 \cos \alpha = u - V_{r_2} \cos \beta$$

but
$$V_{r_2} = V_{r_1} = V_1 - u$$

$$V_2 \cos \alpha = u - (V_1 - u) \cos \beta$$

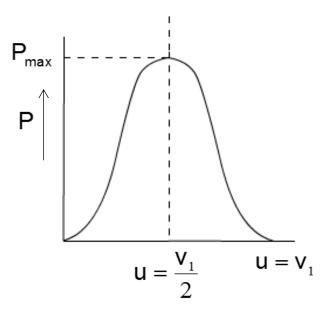
hence

$$F_{x} = \rho A_{1}V_{1}((V_{1} - u) + (V_{1} - u)\cos\beta)$$
$$F_{x} = \rho A_{1}V_{1}(V_{1} - u)(1 + \cos\beta)$$

power developed

$$P = F_{x} * u$$

$$P = \rho A_{1}V_{1}(V_{1} - u)(1 + \cos \beta) * u$$



For max power

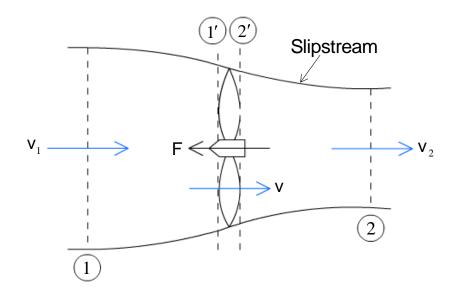
$$\frac{dp}{du} = 0$$

$$\frac{dp}{du} = \rho A_1 V_1 (1 + \cos \beta) (V_1 - 2u) = 0$$

or

$$V_1 - 2u = 0$$
$$u = \frac{1}{2}V_1$$

7. The Screw Propeller



Consider a bulk of fluid within a slipstream accelerated by the screw propeller. The propeller moves forward with a velocity V_1 , thus the fluid a head of the propeller at a section where it is not influenced by the propeller moves relative to the propeller with a velocity V_1 as shown. The fluid through the propeller moves with a velocity V. The propulsive force (Thrust) on the disk formed by the propeller blades is

$$F = \rho Q(V_2 - V_1)$$

The force F on the propeller can also be calculate from.

$$F = (p_{2}^{'} - p_{1}^{'})A$$

Thus

$$p_1' \xrightarrow{\mathsf{F}} \begin{bmatrix} --- \\ --- \end{bmatrix} p_2'$$

$$(p_2' - p_1')A = \rho Q(V_2 - V_1)$$

$$p_{2}^{'} - p_{1}^{'} = \frac{\rho Q}{A} (V_{2} - V_{1})$$

Applying B.E. between sections 1 and 1'

Applying B.E. between sections 2 and 2'

Eq. (3) - Eq. (2)

$$\frac{p_2 - p_1}{\rho g} + \frac{V_2^2 - V_1^2}{2g} = \frac{p_2^{'} - p_1^{'}}{\rho g}$$

 $p_2 = p_1$ (Pressure of surrounding)

$$p_{2}^{'}-p_{1}^{'}=\frac{\rho}{2}(V_{2}^{2}-V_{1}^{2})$$

Substituting in (1)

$$\frac{\rho}{2}(V_2^2 - V_1^2) = \rho V(V_2 - V_1)$$

$$\frac{(V_2 + V_1)(V_2 - V_1)}{2} = V(V_2 - V_1)$$

$$V = \frac{(V_2 + V_1)}{2}$$

The Useful power derived from the propeller.

$$P_{out} = F * V_1$$
$$= \rho Q(V_2 - V_1)V_1$$

B.E. between (1) & (2)

$$\frac{p_1}{\rho g} + \frac{V_1^2}{2g} + E_{prop} = \frac{p_2}{\rho g} + \frac{V_2^2}{2g}$$
$$E_{prop} = \frac{V_2^2 - V_1^2}{2g}$$

Power input = $\rho gQ.E_{prop}$

$$P_{in} = \rho gAV \frac{V_2^2 - V_1^2}{2g}$$

$$P_{in} = \rho AV \left[\frac{(V_2 - V_1)(V_2 + V_1)}{2} \right]$$

But

$$F = \rho AV(V_2 - V_1)$$

Therefore

$$P_{in} = F * V$$

and

$$\eta_{prop} = \frac{P_{out}}{P_{in}} = \frac{V_1}{V}$$