

**Q1:** Calculate LU decomposition to solve the following system of equations:

$$x_1 + x_2 + x_3 = 1 \quad (1)$$

$$4x_1 + 3x_2 - x_3 = 6 \quad (2)$$

$$3x_1 + 5x_2 + 3x_3 = 4 \quad (3)$$

**Q2:** if B is orthogonal matrix, show that  $[B]= \pm 1$

**Q3:** use the data linearization method to find the exponential fit  $y=C e^{Ax}$  for the given data:

x	0	1	2	3	4
y	1.5	2.5	3.5	5	7

**Q4:** define four (4) of the following : 1- Jacobi iterative method 2- unitary matrix 3- relational expressions 4- Newton backward interpolation 5- null matrix

**Q5:** given the following table of values.

x	10	20	30	40	50
y	22	30	41	55	68

Find the difference table using Newton forward interpolation, then evaluate  $f(25)$

**Q6:** Find the inverse of matrix A by elementary row operation.  $A = \begin{bmatrix} 4 & 1 & 2 \\ 5 & 2 & 1 \\ 1 & 0 & 3 \end{bmatrix}$

**Q7:** write three ways for initializing vectors in Matlab.

**Q8:** write the flowchat of the statement (if .... elseif ..... else ..... end)

**Q9:** show that: 1- every eigenvalue of an Hermitian matrix is real 2- different eigenvectors of an Hermitian matrix corresponding to two distinct eigenvalues are orthogonal to each other.

**Q10:** Find the inverse of matrix A by adjoint matrix.  $A = \begin{bmatrix} 1 & -1 & 2 \\ 4 & 0 & 6 \\ 0 & 1 & -1 \end{bmatrix}$

**Q11:** for Dirac matrix prove  $\sigma_l \sigma_m = i \sigma_n$

**Q12:** Find the Lagrange interpolation polynomial that takes the values prescribed below

x	0	1	2	4
f(x)	1	1	2	5

**Q13:** Given the following data

x	3	4	5
y	3	8	7

Find the least square fitting.

**Q14:** put true ( T) or false (F) in front of the following sentences:

- 1- A diagonal matrix is a square matrix where all its elements zeros, except for those in the reverse main diagonal.
- 2- The least square method is restricted to a linear polynomial.
- 3- Eigenvectors of different eigenvalues are orthogonal to one another.
- 4- An Inner product is a Bra multiplied by a Ket.
- 5- The complex equivalent of an orthogonal matrix is the normal matrix.
- 6- The cofactors of a square matrix A is the transpose of the Adjoint matrix.
- 7- If and only if  $\det(A) \neq 0$  , then the square matrix A is singular.

**Q15:** Find the solution of the following system of linear equations, using Gauss-elimination method.

$$3x_1 + x_2 = 2 \quad (1)$$

$$x_2 + 3x_3 = 3 \quad (2)$$

$$x_1 - x_2 + 4x_3 = 5 \quad (3)$$

**Q16:** if  $A = \begin{bmatrix} 0 & 1 & 2 \\ a & 0 & 3 \\ b & c & 0 \end{bmatrix}$  is a skew-symmetric matrix, find a , b and c .

**Q17:** For the Pauli matrices, show that  $\sigma_m \sigma_n + \sigma_n \sigma_m = 2 I \delta_{mn}$  , where  $\delta_{mn}$  is kronecker delta

**Q18:** Given the data :

x	1	2	2.5	3
y	3.7	4.1	4.3	5

Find the least square fitting to these data

**Q19:** write the work of the following functions and commands :

- 1- eye (m,n)
- 2- abs(x)
- 3- prod(x)
- 4- tril (y)
- 5- format bank

**Q20:** Find the inverse of matrix A by adjoint matrix.  $A = \begin{bmatrix} 4 & 1 & 2 \\ 5 & 2 & 1 \\ 1 & 0 & 3 \end{bmatrix}$

**Q21:** write three ways for drawing multiple plots on the same set of axes.

**Q22:** write the flowchart of the statement (switch..... case)

**Q23:** show which of the following matrices singular or non-singular.

$$1- A = \begin{bmatrix} 4 & 0 & 3 \\ 5 & 1 & 2 \\ -1 & 6 & 2 \end{bmatrix} \quad 2- A = \begin{bmatrix} 0 & 2 & -1 \\ 3 & -2 & 1 \\ 3 & 2 & -1 \end{bmatrix}$$

**Q24:** what are the ways of drawing multiple plots on the same set of axes.

**Q25:** what are the main difference between functions (display and fprintf)

**Q26:** what are the work of the following: 1- nthroot (z,n) 2- rem (y,x) 3- triu (f) 4- grid  
5- fplot

**Q27:** fill the blanks with correct answer:

1- The function ----- is use to rounding the result toward zero.

round      b- fix      c- floor      d- ceil

2- The max. length of variable name in matlab is ----- character .

a- 32      b- 31      c- 30      d- 33

3- title('text') :writes the text as a title on ----- of the graph.

a- Right      b- Left      c- Top      d- down

4- If you need to set the same scale for both axes, we use command ----- .

a- axis square      axis tight      c- axis equal      d- axis ([ x<sub>min</sub> x<sub>max</sub> ])

5- If we are plotting two graphs on the same axes, we may find ----- useful. It allows to have independent y-axis labels on the left and right.

Ploty (x,y)      b- plotyy(x,y)      c- plot( x1,y1,x2,y2)      d- plot(x)

**Q28:** write the flowchart of ( if ---- elseif ----- else -----end)

**Q29:** what are the ways to entering variables to Matlab .

Q30: what are the work of the following: 1-  $A(:,S:R)$  2-  $\text{conj}(t)$  3-  $\text{rot90}(B,3)$   
 4-  $\text{hist}(F,4)$  5-  $\text{csch}(h)$

Q31: Define the following: 1- Upper triangular matrix 2- orthogonal matrices  
 3- orthogonally diagonalizable 4-  $\text{isempty}(x)$  logical function 5- histogram

Q32: prove that the interchange of any two rows will alter the sign but not the numerical value of a determinant

Q33: find the solution of the following system of equations by matrix inversion.

$$x_1 + x_2 + x_3 = 1 \quad (1)$$

$$4x_1 + 3x_2 - x_3 = 6 \quad (2)$$

$$3x_1 + 5x_2 + 3x_3 = 4 \quad (3)$$

Q34: show that the following matrix is Hermitian matrix:

$$A = \begin{bmatrix} 3 & 1-i & -i \\ 1+i & -2 & 2+i \\ i & 2-i & 5 \end{bmatrix}$$

Q35: describe this plot:

```
plot(z,p,':sk','LineWidth',6,'markersize',10,'MarkerEdgeColor',  
'c','markerfacecolor','b')
```

Q36: Find the inverse of matrix x by elementary row operation.  $A = \begin{bmatrix} 4 & 1 & 2 \\ 5 & 2 & 1 \\ 1 & 0 & 3 \end{bmatrix}$

Q37: show that : 1- every eigenvalue of an Hermitian matrix is real 2-different eigenvectors of an Hermitian matrix corresponding to two distinct eigenvalues are orthogonal to each other.

Q38: write the flowchat of the statement (if...elseif...else...end)

Q39: for Dirac matrix prove  $\sigma_l \sigma_m = i \sigma_n$

Q40: If  $\mathbf{B}$  is orthogonal matrix, show that  $[\mathbf{B}] = \pm 1$

Q41: Choose the correct answer:

1- The complex equivalent of an orthogonal matrix is the ----- matrix.

- a- Symmetric                      b- Hermition                      c- unitary                      d- normal

2- In determinant rules: the addition of a multiple of any row to another row will -----

- a- alter the sign but not its numerical value                      b- leave it unaltered  
 c- make determinant zero                      d- changed its value

3- Any square matrix may be written as the sum of :

- a- symmetric & orthogonal matrices    c- symmetric & skew-symmetric matrices  
 b- unitary & normal matrices            d- orthogonal & normal matrices

4- A square matrix where all its elements zeros, except for those in the main diagonal is called -----

- a- Identity                      b- null                      c- diagonal                      d- symmetric

5- The simplest method to find inverse of the matrix is by:

- a- Adjoint method                      b- Crammer method                      c- elementary row operation    d- matlab prog.

**Q42:** Find the inverse of matrix A by elementary row operation.  $A = \begin{bmatrix} 0 & 2 & -1 \\ 3 & -2 & 1 \\ 3 & 2 & 1 \end{bmatrix}$

**Q43:** For Dirac matrices, prove that  $\sigma_l \sigma_m = i \sigma_n$ .

Q44: write the flowchat of the statement (switch ....case)

**Q45:** for the given data:

X	1	2	3
f(x)	8	4	7

Find the Lagrange interpolation polynomial  $p_n(x)$  of these data points, then estimate  $f(x)$  for  $x=2.5$

Q46: Define the following :

- 1- Orthogonally diagonalizable                      2- normal matrix                      3- skew-symmetric matrix  
 4- outer product                      5- relational expressions

Q46: for the given data, find the  $f(25)$ , of these data points using Newton forward interpolation polynomial.

x	10	20	30	40	50
y = f(x)	46	66	81	93	101