

# **Linear Algebra (II)**

**2022-2023**

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# Chapter 1: Linear transformations

## 1.1 Examples and elementary properties.

### Definition 1.1.1:

Let  $V$  and  $W$  be two vector spaces over the same field  $F$ . A mapping  $T:V \rightarrow W$  is called a linear transformation if it is satisfied the following axioms

1.  $T(v_1+v_2) = T(v_1) + T(v_2)$ , where  $v_1, v_2 \in V$ .
2.  $T(\lambda v) = \lambda T(v)$ , where  $v \in V$  and  $\lambda \in F$ .

In a linear transformation  $T$ , if  $V=W$ , then  $T$  is called a linear operator on  $V$ .

### Theorem 1.1.2:

Let  $V$  and  $W$  be two vector spaces over the same field  $F$ . A mapping  $T:V \rightarrow W$  is linear transformation if and only if

$$v_1, v_2 \in V \wedge \lambda, \mu \in F \rightarrow T(\lambda v_1 + \mu v_2) = \lambda T(v_1) + \mu T(v_2).$$

### Example 1.1.3:

- i. Consider the vector spaces  $\mathfrak{R}^2$  and  $\mathfrak{R}^3$  over  $\mathfrak{R}$ , define
  1.  $T: \mathfrak{R}^2 \rightarrow \mathfrak{R}^3$  such that  $T(x, y) = (x+y, 3x-4y, 2y)$
  2.  $T: \mathfrak{R}^2 \rightarrow \mathfrak{R}^3$  such that  $T(x, y) = (x-y, x+y-1, x)$
  3.  $T: \mathfrak{R}^2 \rightarrow \mathfrak{R}^2$  such that  $T(x, y) = (xy, x)$
- ii. Consider the vector spaces  $P_{n-1}$ ,  $P_n$  and  $P_{n+1}$ 
  1.  $T: P_n \rightarrow P_{n-1}$  such that  $T(p(x)) = \frac{dp(x)}{dx}$
  2.  $T: P_n \rightarrow P_{n+1}$  such that

$$T(p(x)) = \int_0^x p(t) dt$$

**Theorem 1.1.4:**

Let  $T:V \rightarrow W$  be a linear transformation, then

1.  $T(0)=0$ .
2.  $u \in V \rightarrow T(-u)=-T(u)$ ,

**Definition 1.1.5:**

1. The linear operator  $I_V:V \rightarrow V$  such that  $I_V(v)=v, \forall v \in V$  is called the identity operator on  $V$ .
2. The linear transformation  $0:V \rightarrow W$  such that  $0(v)=0, \forall v \in V$  is called the zero transformation.

**Theorem 1.1.6:**

Let  $T, S:V \rightarrow W$  be two linear transformations such that  $V = \text{span}(\{v_1, \dots, v_n\})$ . If  $T(v_i)=S(v_i), \forall i, 1 \leq i \leq n$ , then  $T=S$ .

**Exercise 1.1.7:**

- i. Verify whether the following functions are linear transformations or not.
  1.  $T:\mathbb{R}^2 \rightarrow \mathbb{R}^2$  such that  $T(x, y)=(x, -y)$ .
  2.  $T:C \rightarrow C$  such that  $T(z)=\bar{z}$ .
  3.  $S:M_{n \times n} \rightarrow M_{n \times n}$  such that  $S(A)=A+A^T$ .
- ii. Let  $T:V \rightarrow W$  be a linear transformation,  $\{v_1, \dots, v_n\} \subseteq V$ . If  $\{T(v_1), \dots, T(v_n)\}$  is linearly independent, then so is  $\{v_1, \dots, v_n\}$ .

**1.2 Kernel and image of linear transformation****Definition 1.2.1:**

Let  $T:V \rightarrow W$  be a linear transformation, the kernel and the image of  $T$  is defined as follows

$$\ker(T) = \{v \in V | T(v) = 0\}.$$

$$\text{img}(T) = \{w \in W | w = T(v), \text{ for some } v \in V\}.$$

**Example 1.2.2:**

Let  $T:\mathbb{R}^3 \rightarrow \mathbb{R}^3$  be a mapping defined by  $T(x, y, z) = (x-y, z, y-x)$ .

1. Show that  $T$  is a linear transformation.
2. Find  $\ker(T)$  and  $\text{img}(T)$ .

**Solution:**

$\ker(T) = \{(x, x, 0) | x \in \mathbb{R}\}$  and  $\text{img}(T) = \{(a, b, -a) | a, b \in \mathbb{R}\}$ .

**Example 1.2.3:**

Let  $S:M_{n \times n} \rightarrow M_{n \times n}$  be a linear transformation such that  $S(A) = A - A^T$ . Find  $\ker(T)$  and  $\text{img}(T)$ .

**Theorem 1.2.4:**

For any linear transformation  $T:V \rightarrow W$ ,  $\ker(T)$  is a subspace of  $V$  and  $\text{img}(T)$  is a subspace of  $W$ .

**Theorem 1.2.5:**

Any linear transformation  $T:V \rightarrow W$  is 1-1 if and only if  $\ker(T) = \{0\}$ .

**Example 1.2.6:**

Let  $S:\mathbb{R}^2 \rightarrow \mathbb{R}^3$  and  $T:\mathbb{R}^3 \rightarrow \mathbb{R}^2$  be linear transformation such that. Apply **Theorem 1.2.5** for each of the following

1.  $T(x, y, z) = (x+y, x-y)$ .
2.  $S(x, y) = (x+y, x-y, x)$ .

**Exercise 1.2.7:**

Let  $T:V \rightarrow W$  be a linear transformation, prove or disprove

1.  $\ker(T) = V \rightarrow W = \{0\}$ .
2.  $V = W \rightarrow \ker(T) \subseteq \text{img}(T)$ .
3.  $W = \{0\} \subseteq \ker(T) = V$ .
4.  $V = W \wedge \text{img}(T) \subseteq \ker(T) \rightarrow T = 0$ .

## 1.3 Isomorphism and composition

### Definition 1.3.1:

A linear transformation  $T:V \rightarrow W$  is called isomorphism if  $T$  is 1-1 and onto. Two vector spaces are called isomorphic if there is an isomorphism between them. We use the notation  $V \cong W$ .

### Example 1.3.2:

1. The identity linear transformation on  $V$  is isomorphism.
2.  $S: M_{n \times n} \rightarrow M_{n \times n}$  such that  $S(A) = A^T$  is an isomorphism.
3. The zero linear transformation  $T:V \rightarrow W$  is not isomorphism.

### Theorem 1.3.3:

Let  $T:V \rightarrow W$  be a linear transformation for which  $V$  and  $W$  are finite dimensional. Then the following statements are equivalent

1.  $T$  is an isomorphism.
2. If  $\{v_1, \dots, v_n\}$  is a basis of  $V$ , then  $\{T(v_1), \dots, T(v_n)\}$  is a basis of  $W$ .
3. There exists a base  $\{v_1, \dots, v_n\}$  of  $V$ , such that  $\{T(v_1), \dots, T(v_n)\}$  is a basis of  $W$ .

### Theorem 1.3.4:

Let  $V$  and  $W$  be two finite dimensional vector spaces. Then

$$V \cong W \leftrightarrow \dim(V) = \dim(W).$$

### Proof:

Let  $V \cong W$ , then  $\exists$  an isomorphism  $T:V \rightarrow W$ .

Suppose  $\{r_1, \dots, r_m\}$  be a base of  $V$ , then by **Theorem 1.3.3**,  $\{T(r_1), \dots, T(r_m)\}$  is a basis of  $W$ .

On the other hand,  $T(r_i) \neq T(r_j)$ , since  $T$  is 1-1, then  $\dim(V) = \dim(W)$ .

Conversely, let  $\{v_1, \dots, v_n\}$  and  $\{w_1, \dots, w_n\}$  be basis for  $V$  and  $W$  respectively.

Define  $T:V \rightarrow W$  as follows

1.  $T(v_i) = w_i$ .

2. For  $v \in V$ , we have  $v = a_1v_1 + \dots + a_nv_n$  then we define

$$T(v) = a_1T(v_1) + \dots + a_nT(v_n) = a_1w_1 + \dots + a_nw_n.$$

Is  $T$  well defined?

$$v_i = v_j \rightarrow T(v_i) = T(v_j).$$

Otherwise  $\dim(V) \neq \dim(W)$ .

$$v = v^* \rightarrow v = a_1v_1 + \dots + a_nv_n = v^* \rightarrow T(v) = a_1T(v_1) + \dots + a_nT(v_n) = T(v^*).$$

To show that  $T$  is a linear transformation,

1. Let  $v, v^* \in V$ , then

$$v = b_1v_1 + \dots + b_nv_n \text{ and } v^* = c_1v_1 + \dots + c_nv_n.$$

$$\begin{aligned} T(v + v^*) &= T((b_1v_1 + \dots + b_nv_n) + (c_1v_1 + \dots + c_nv_n)) \\ &= T((b_1 + c_1)v_1 + \dots + (b_n + c_n)v_n) \\ &= (b_1 + c_1)T(v_1) + \dots + (b_n + c_n)T(v_n) \\ &= (b_1T(v_1) + \dots + b_nT(v_n)) + (c_1T(v_1) + \dots + c_nT(v_n)) \\ &= T(v) + T(v^*) \end{aligned}$$

2. Let  $v \in V$  and  $\lambda$  be a scalar,

$$\begin{aligned} T(\lambda v) &= T(\lambda(a_1v_1 + \dots + a_nv_n)) = T(\lambda a_1v_1 + \dots + \lambda a_nv_n) = \lambda a_1T(v_1) + \dots + \lambda a_nT(v_n) \\ &= \lambda(a_1T(v_1) + \dots + a_nT(v_n)) = \lambda T(v). \end{aligned}$$

For 1-1,

$$\text{Let } T(v) = T(v^*)$$

$$T(v) = T(v^*) \rightarrow v = v^* \text{ (Homework).}$$

For onto,

Let  $w \in W$

$$w \in W \rightarrow w = a_1w_1 + \dots + a_nw_n = a_1T(v_1) + \dots + a_nT(v_n) = T(a_1v_1 + \dots + a_nv_n) = T(v), \text{ for some } v \in V.$$

**Example 1.3.5:**

$P_2$  and the set of all symmetric matrices of order two are isomorphic.

**Dimension Theorem:**

Let  $T:V \rightarrow W$  be a linear transformation for which  $\ker(T)$  and  $\text{img}(T)$  are finite dimensional, then  $V$  is finite dimensional and

$$\dim(\ker(T)) + \dim(\text{img}(T)) = \dim(V)$$

**Proof:**

Not required.

**Theorem 1.3.6:**

Let  $V$  and  $W$  be two finite dimensional vector spaces of the same order. A linear transformation  $T:V \rightarrow W$  is an isomorphism if  $T$  is either 1-1 or onto.

**Exercise 1.3.7:**

Let  $T:\mathbb{R}^3 \rightarrow \mathbb{R}^3$  be a linear transformation such that  $T(x, y, z) = (x+y, y+z, x+z)$ . Is  $T$  an isomorphism?

**Theorem 1.3.8:**

Let  $T:V \rightarrow W$  and  $S:W \rightarrow Z$  be linear transformations, then

1.  $SoT$  is a linear transformation, where  $SoT$  is the composition function of  $T$  and  $S$ .
2. If  $T$  and  $S$  are isomorphisms, then so is  $SoT$ .

**Proof:**

$$SoT(v_1+v_2) = S(T(v_1+v_2)) \quad (\text{Definition of composition of functions})$$

$$= S(T(v_1)+T(v_2)) \quad (T \text{ is L.T.})$$

$$= S(T(v_1))+S(T(v_2)) \quad (S \text{ is L.T.})$$

$$= SoT(v_1)+SoT(v_2) \quad (\text{Why?})$$

$$SoT(\lambda v) = S(T(\lambda v)) = S(\lambda T(v)) = \lambda S(T(v)) = \lambda SoT(v)$$

2.  $S$  and  $T$  are bijective  $\rightarrow$   $SoT$  is bijective.

Then from 1. and 2.  $SoT$  is isomorphism.

**Definition 1.3.9:**

Let  $V$  and  $W$  be vector spaces,  $T:V \rightarrow W$  and  $S:W \rightarrow V$  be linear transformations. We say that  $S$  is the inverse of  $T$  if

$$ToS=I_W \text{ and } SoT=I_V.$$

The inverse of  $T$  is denoted by  $T^{-1}$ .

A linear transformation  $T$  is called invertible if it has the inverse.

Notice that if  $S$  is the inverse of  $T$ , then  $T$  is the inverse of  $S$ .

**Exercise 1.3.10:**

A linear transformation  $T$  has the inverse if and only if  $T$  is 1-1 and onto.

**Example 1.3.11:**

Verify whether the following transformation is invertible or not.

1.  $T:\mathbb{R}^3 \rightarrow \mathbb{R}^3$  such that  $T(x, y, z) = (x+y, y+z, x+z)$

$$\left( \begin{array}{ccc|c} 2 & 0 & 0 & u - v + w \\ 0 & -2 & 0 & -u - v + w \\ 0 & 0 & 2 & -u + v + w \end{array} \right)$$

2.  $T:\mathbb{R}^4 \rightarrow \mathbb{R}^4$  such that  $T(x, y, z, w) = (x+y, y+z, z+w, x+w)$

$$\left( \begin{array}{cccc} 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 1 \end{array} \right)$$

**Exercise 1.3.12:**

- i. Find a linear transformation with the given properties and compute  $T(v)$ :

1.  $T:\mathbb{R}^2 \rightarrow \mathbb{R}^3$ ;  $T(1,2)=(1,0,1)$ ,  $T(-1,0)=(0,1,1)$ ,  $v=(-3,2)$
2.  $T:\mathbb{P}_2 \rightarrow \mathbb{P}_3$ ,  $T(x^2)=x^3$ ,  $T(x+1)=0$ ,  $T(x-1)=x$ ,  $v=x^2+x+1$ .



Remark:

Step 1: Show that  $\{(1,2),(-1,0)\}$  is a base of  $\mathfrak{R}^2$ .

Step 2: Write  $v=(-3,2)$  as a linear combination of  $(1,2)$  and  $(-1,0)$ .

$$(-3,2)=1(1,2)+4(-1,0)$$

Step 3: Take  $T$  for Step 2,

$$T(-3,2)=T(1(1,2)+4(-1,0))$$

$$=1T(1,2)+4T(-1,0)$$

$$=1(1,0,1)+4(0,1,1)=(1,4,5).$$

ii. Verify whether the following linear transformations are isomorphism or not

1.  $T:P_1 \rightarrow \mathfrak{R}^2$  such that  $T(p(x))=(p(0), p(1))$ .

2.  $T:V \rightarrow V$ ,  $T(v)=\lambda v$ ,  $\lambda$  is a nonzero scalar.

3.  $T:P_2 \rightarrow P_2$  such that  $T(p(x))=p(x+1)$ .

iii. Is the linear transformation  $T$  that is defined in **Exercise 1.3.12**, *i*. isomorphism?

## 1.4 Operations with linear transformations

### Definition 1.4.1:

Let  $T:V \rightarrow W$  and  $S:V \rightarrow W$  be linear transformations. Define

1. The sum  $(T \oplus S)$  of  $T$  and  $S$  as a function from  $V$  to  $W$  as follows

$$(T \oplus S)(v) = T(v) + S(v). \quad \forall v_1, v_2 \in V.$$

2. The scalar product  $\lambda T$  from  $V$  to  $W$  as follows:

$$(\lambda \odot T)(v) = \lambda T(v). \quad \forall v \in V \text{ and } \lambda \in F.$$

### Theorem 1.4.2:

Let  $V$  and  $W$  be vector spaces over the same field  $F$ , then the collection of all linear transformations with the operations defined in **Definition 1.4.1** is a vector space denoted by  $\text{Hom}(V, W)$ .

**Proof:**

$\text{Hom}(V, W) = \{T | T: V \rightarrow W \text{ is a linear transformation}\}$

We have to show that  $\text{Hom}(V, W)$  with the operations  $\oplus$  and  $\odot$  is a vector space over the field  $F$ .

For associativity  $(T \oplus S) \oplus U = T \oplus (S \oplus U)$

$$\begin{aligned}(T \oplus S) \oplus U(v) &= (T \oplus S)(v) \oplus U(v) = (T(v) \oplus S(v)) \oplus U(v) = T(v) \oplus (S(v) \oplus U(v)) = T(v) \oplus (S \oplus U)(v) \\ &= T \oplus (S \oplus U)(v).\end{aligned}$$

For commutativity, homework

The zero transformation is the identity.

For any  $T: V \rightarrow W$ ,  $-T: V \rightarrow W$  is the inverse of  $T$ .

For  $(\lambda + \mu) \odot T = (\lambda + \mu) \odot T$  ?

$$(\lambda + \mu) \odot T(v) = (\lambda + \mu)T(v) = \lambda T(v) + \mu T(v) = \lambda \odot T(v) + \mu \odot T(v).$$

The others are homework.

**Theorem 1.4.3:**

Let  $V$  and  $W$  be two vector space such that  $\dim(V) = m$  and  $\dim(W) = n$ . Then  $\dim(\text{Hom}(V, W)) = mn$ .

**Proof: Not required.**

## 1.5 Matrix representation of a linear transformation

### Definition 1.5.1:

Let  $A_{m \times n}$  be a matrix. The matrix transformation  $T_A: \mathfrak{R}^n \rightarrow \mathfrak{R}^m$  is defined by

$$T_A(X) = AX, \text{ where } X \in \mathfrak{R}^n.$$

### Theorem 1.5.2:

For each matrix  $A_{m \times n}$ , the matrix transformation  $T_A$  defined in **Definition 1.5.1** is a linear transformation.

### Proof:

$$T_A(\lambda X + \mu Y) = A(\lambda X + \mu Y) \quad (\text{By Definition 1.5.1})$$

$$= A(\lambda X) + A(\mu Y) \quad (\text{Matrix property})$$

$$= \lambda AX + \mu AY \quad (\text{Matrix property})$$

$$= \lambda T_A(X) + \mu T_A(Y)$$

### Example 1.5.3:

For each of the following matrices, find  $T_A$

1.  $A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$

2.  $A = \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}$

### Solution:

1.  $T_A(X) = T_A\left(\begin{pmatrix} x \\ y \end{pmatrix}\right) = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} y \\ x \end{pmatrix}$

2.  $T_A(X) = T_A\left(\begin{pmatrix} x \\ y \end{pmatrix}\right) = \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 2x \\ y \end{pmatrix}$

### Exercise 1.5.4:

Find the matrix transformation of the matrix  $A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$ .

## Chapter 2: Eigenvalues and Dignonalisation

### 2.1 Eigenvalues and similarity

#### Definition 2.1.1:

Let  $A$  be a square matrix of order  $n$ . A scalar  $\lambda$  (real or complex) is said to be an eigenvalue of  $A$  if,

$$\exists \text{ a nonzero column vector } X \text{ such that } AX = \lambda X. \dots(2.1)$$

In this case,  $X$  is called an eigenvector of  $A$  corresponding to  $\lambda$ .

#### Definition 2.1.2:

Let  $\lambda$  be an eigenvalue of the matrix  $A_{n \times n}$ . The set of all eigenvectors defined in **Definition 2.1.1** is called the eigenspace associated to  $\lambda$ , i.e.

$$E_\lambda(A) = \{ X \mid AX = \lambda X \}.$$

#### Theorem 2.1.3:

For each  $\lambda$ , the set  $E_\lambda(A)$  is a subspace of  $(\mathfrak{R}^n \text{ or } C^n)$ .

#### Remark 2.1.4:

The equation (2.1) is the same as the equation  $(A - \lambda I_n)X = 0$ .

#### Definition 2.1.5:

The determinant of the equation  $A - \lambda I_n = 0$  is called the characteristic polynomial of the matrix  $A_{n \times n}$ , and denoted by  $c_A(\lambda)$ ,

$$c_A(\lambda) = \det(A - \lambda I_n)$$

Clearly, the eigenvalues of a matrix  $A$  is the roots (zeros) of the characteristic polynomial and vice versa.

#### Example 2.1.6:

Find the eigenvalues and the eigenspace of the following matrices

$$1. A = \begin{pmatrix} 2 & 3 \\ 1 & 4 \end{pmatrix}$$

$$2. A = \begin{pmatrix} 1 & -2 & 3 \\ 2 & 6 & -6 \\ 1 & 2 & -1 \end{pmatrix}$$

**Solution:**

$$p(\lambda) = |A - \lambda I_2| = \begin{vmatrix} 2 & 3 \\ 1 & 4 \end{vmatrix} - \lambda \begin{vmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix} = \begin{vmatrix} 2 - \lambda & 3 \\ 1 & 4 - \lambda \end{vmatrix} = \lambda^2 - 6\lambda + 5.$$

The eigenvalues are  $\lambda=5$  and  $\lambda=1$ .

For the eigenvector of  $\lambda=5$ , we apply

$AX = \lambda X$ , then

$$\begin{pmatrix} 2 & 3 \\ 1 & 4 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = 5 \begin{pmatrix} x \\ y \end{pmatrix} \rightarrow \begin{pmatrix} 2x + 3y \\ x + 4y \end{pmatrix} = \begin{pmatrix} 5x \\ 5y \end{pmatrix}$$

Then, we obtain  $y=x$ .

So, the eigenvector of  $\lambda=5$  is  $\begin{pmatrix} x \\ x \end{pmatrix}$

$$E_5\left(\begin{pmatrix} 2 & 3 \\ 1 & 4 \end{pmatrix}\right) = \text{span}\left\{\begin{pmatrix} 1 \\ 1 \end{pmatrix}\right\}.$$

For the eigenvector of  $\lambda=1$ ,

$$\begin{pmatrix} 2 & 3 \\ 1 & 4 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = 1 \begin{pmatrix} x \\ y \end{pmatrix} \rightarrow \begin{pmatrix} 2x + 3y \\ x + 4y \end{pmatrix} = \begin{pmatrix} x \\ y \end{pmatrix}$$

Then, we obtain  $y = -\frac{x}{3}$ .

So, the eigenvector of  $\lambda=1$  is  $\begin{pmatrix} -3 \\ 1 \end{pmatrix}$

$$E_1\left(\begin{pmatrix} 2 & 3 \\ 1 & 4 \end{pmatrix}\right) = \text{span}\left\{\begin{pmatrix} -3 \\ 1 \end{pmatrix}\right\}.$$

**Definition 2.1.7:**

An eigenvalue  $\lambda$  is said to be of multiplicity  $m$  if it is repeated  $m$  times.

$$c_A(\lambda) = (x - \lambda)^m q(x)$$

**Example 2.1.8:**

$$A = \begin{pmatrix} 5 & 8 & 16 \\ 4 & 1 & 8 \\ -4 & -4 & 11 \end{pmatrix}$$

$\lambda=1$  and  $\lambda=-3$  (with multiplicity two) are the eigenvalues of  $A$ .

$$E_1(A) = \text{span} \left\{ \begin{pmatrix} 2 \\ 1 \\ -1 \end{pmatrix} \right\} \text{ and } E_{-3}(A) = \text{span} \left\{ \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -2 \\ 0 \\ 1 \end{pmatrix} \right\}.$$

**Exercise 2.1.9:**

Find the eigenvalues and the eigenspace of the following matrix.

$$A = \begin{pmatrix} 1 & -2 & 3 \\ 2 & 6 & -6 \\ 1 & 2 & -1 \end{pmatrix}$$

**Theorem 2.1.10:**

If  $\lambda$  is an eigenvalue of a matrix  $A$  with the nonzero eigenvector  $X$ , then  $\lambda^2$  is an eigenvalue of the matrix  $A^2$  with the same eigenvector  $X$ .

**Proof:**

$$|A^2 - \lambda^2 I| = |A^2 - \lambda^2 I^2| = |(A - \lambda I)(A + \lambda I)| = |A - \lambda I| |A + \lambda I| = 0. \quad |A + \lambda I| = 0.$$

Then  $\lambda^2$  is an eigenvalue of  $A^2$ .

$$A^2 X = A(AX) = A(\lambda X) = \lambda(AX) = \lambda(\lambda X) = \lambda^2 X.$$

Then  $X$  is the eigenvector of  $A^2$  corresponding to  $\lambda^2$ .

**Exercise 2.1.11:**

Regarding to **Theorem 2.1.10**, show that  $\lambda^3 - 2\lambda + 3$  is an eigenvalue of the matrix  $A^3 - 2A + 3I$ .

**Example 2.1.12:**

For a triangular matrix  $A = (a_{ij})$ , the set of eigenvalues are the entries of the main diagonal.

**Solution:**

Let  $A$  be an upper triangular matrix of order  $n$ . Then,

$$c_A(\lambda) = |A - \lambda I_n| = \prod_{i=1}^n (a_{ii} - \lambda)$$

Then  $\lambda = a_{ii}$ , for all  $i=1, \dots, n$ .

Similarly, for the lower triangular matrix.

**Example 2.1.13:**

Prove that  $A$  and  $A^T$  have the same eigenvalues.

**Solution:**

Let  $A$  be a square matrix of order  $n$ . Then,

for  $A^T$ , the characteristic polynomial is given by,

$$c_{A^T}(\lambda) = |A^T - \lambda I_n| = |(A - \lambda I_n)^T| = |A - \lambda I_n|.$$

**Definition 2.1.14:**

Let  $A$  and  $B$  be two square matrices of the same order, we say that  $A$  and  $B$  are similar if  $B = P^{-1}AP$  or  $B = PAP^{-1}$ , for some invertible matrix  $P$ .

We use the expression  $(A \sim B)$  for two similar matrices  $A$  and  $B$ .

**Example 2.1.15:**

Let  $A = \begin{pmatrix} 2 & 1 \\ -1 & -1 \end{pmatrix}$ . Show that  $A \sim B$  if  $B = \begin{pmatrix} -2 & 5 \\ -1 & 3 \end{pmatrix}$ .

**Solution:**

We may select  $P = \begin{pmatrix} -1 & 3 \\ 1 & -2 \end{pmatrix}$ . Then

$$P^{-1}AP = \begin{pmatrix} 2 & 3 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 2 & 1 \\ -1 & -1 \end{pmatrix} \begin{pmatrix} -1 & 3 \\ 1 & -2 \end{pmatrix} = \begin{pmatrix} 1 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} -1 & 3 \\ 1 & -2 \end{pmatrix} = \begin{pmatrix} -2 & 5 \\ -1 & 3 \end{pmatrix}$$

**Theorem 2.1.16:**

Let  $A \sim B$ , then

1.  $A^{-1} \sim B^{-1}$ .

2.  $\lambda A \sim \lambda B$ .
3.  $A^T \sim B^T$ .

**Proof:**

1.  $A \sim B \rightarrow \exists$  an invertible matrix  $P$  such that  $B = P^{-1}AP$ .  
 $\rightarrow \exists$  an invertible matrix  $P$  such that  $B^{-1} = (P^{-1}AP)^{-1}$   
 $\rightarrow \exists$  an invertible matrix  $P$  such that  $B^{-1} = P^{-1}A^{-1}(P^{-1})^{-1}$   
 $\rightarrow \exists$  an invertible matrix  $P$  such that  $B^{-1} = P^{-1}A^{-1}P$ .

**Theorem 2.1.17:**

Let  $A$  and  $B$  be two similar matrices, then

1.  $A$  and  $B$  have the same determinant.
2.  $A$  and  $B$  have the same trace.
3.  $A$  and  $B$  have the same characteristics polynomial.
4.  $A$  and  $B$  have the same eigenvalues.

**Proof:**

1.  $|B| = |P^{-1}AP| = |A| |P^{-1}|$ .
2.  $\text{trace}(B) = \text{trace}(P^{-1}AP) = \text{trace}(AP^{-1}P) = \text{trace}(AI_n) = \text{trace}(A)$ .
3.  $c_B(\lambda) = |B - \lambda I| = |P^{-1}AP - \lambda I| = |P^{-1}AP - \lambda P^{-1}P| = |P^{-1}AP - P^{-1}\lambda P| = |P^{-1}(AP - \lambda P)| = |P^{-1}| |AP - \lambda P|$   
 $= |P^{-1}| |(A - \lambda I)P| = |P^{-1}| |A - \lambda I| |P| = |A - \lambda I| = c_A(\lambda)$ .

**Theorem 2.1.18:**

If  $A \sim B$ , then  $\text{rank}(A) = \text{rank}(B)$ .

**Remark 2.1.19:**

1. The converse of all tasks that mentioned in **Theorem 2.1.17** need not be true.
2. The converse of **Theorem 2.1.18** need not be true.

**Example 2.1.20:**

The matrix  $A = \begin{pmatrix} 1 & 2 \\ 0 & 1 \end{pmatrix}$  and  $I_2$  are not similar, while,



1.  $|A|=|I_2|$ .
2.  $\text{trace}(A)=\text{trace}(I_2)$ .
3.  $\text{rank}(A)=\text{rank}(I_2)$ .
4. The eigenvalue of  $A$  is  $\lambda=1$  with multiplicity 2.

**Theorem 2.1.21:**

Let  $\Psi$  be the set of all square matrices of order  $n$ . Define a relation  $R$  as follows,

$$R=\{(A,B)\in\Psi\times\Psi|A\sim B\}.$$

Then  $R$  is an equivalence relation on  $\Psi$ .

**Exercise 2.1.22:**

- i. Find the eigenvalues and eigenspaces of the following matrices,

1.  $A = \begin{pmatrix} 1 & 2 \\ 3 & 2 \end{pmatrix}$

2.  $A = \begin{pmatrix} 2 & 1 & 1 \\ 0 & 1 & 0 \\ 1 & -1 & 2 \end{pmatrix}$

3.  $A = \begin{pmatrix} \cos x & \sin x \\ -\sin x & \cos x \end{pmatrix}$

- ii. Let  $A = \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix}$  and  $B = \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix}$ . Is  $A\sim B$ ?

## 2.2 Diagonalisation

**Definition 2.2 1:**

A real square matrix  $A$  of order  $n$  is said to be diagonalisable if it is similar to a diagonal matrix. That is,

$$P^{-1}AP \text{ is diagonalisable, for some invertible matrix } P.$$

**Theorem 2.2.2:**

A square matrix  $A$  of order  $n$  is diagonalisable if and only if it has  $n$  linearly independent eigenvectors.

**Proof:**

Step 1: Let  $A$  be a diagonalisable matrix of order  $n$ ,

Then

$$D = P^{-1}AP = \begin{pmatrix} \lambda_1 & 0 & \cdots & 0 \\ 0 & \lambda_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & \cdots & 0 & \lambda_n \end{pmatrix}$$

Step 2: We find  $P$  by finding each of its columns,  $P=(X_1 \ X_2 \ \dots \ X_n)$ .

Step 3: From Step 1, we have  $AP=PD$ , then,

$$A(X_1 \ X_2 \ \dots \ X_n) = (X_1 \ X_2 \ \dots \ X_n) \begin{pmatrix} \lambda_1 & 0 & \cdots & 0 \\ 0 & \lambda_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & \cdots & 0 & \lambda_n \end{pmatrix}$$
$$\rightarrow (AX_1 \ AX_2 \ \dots \ AX_n) = (\lambda_1 X_1 \ \lambda_2 X_2 \ \dots \ \lambda_n X_n)$$
$$\rightarrow AX_i = \lambda_i X_i, \ i=1, \dots, n.$$

So,  $X_i, \ i=1, \dots, n$  are the eigenvectors of  $A$  corresponds to the eigenvalues  $\lambda_i, \ i=1, \dots, n$  respectively.

Previous result: A matrix  $P$  is invertible if and only if its columns are linearly independent.

Then  $X_i, \ i=1, \dots, n$  are linearly independent.

Conversely, if  $X_i, \ i=1, \dots, n$  are linearly independent, then  $P=(X_1 \ X_2 \ \dots \ X_n)$  is invertible, hence we obtain  $AP=PD$ , or equivalently,  $D=P^{-1}AP$ .

**Diagonalisation Algorithm**

Let  $A$  be a square matrix of order  $n$ ,

1. Find the eigenvalues of  $A$ .
2. Find  $n$  eigenvectors if possible  $X_1, \dots, X_n$ .
3. Select  $P=[ X_1 \ X_2 \ \dots \ X_n]$
4.  $P^{-1}AP$  is diagonal.

**Example 2.2.3:**

Determine whether the following matrices are diagonalisable or not

$$1. A = \begin{pmatrix} 2 & -4 \\ -1 & 2 \end{pmatrix}$$

$$2. A = \begin{pmatrix} 5 & 8 & 16 \\ 4 & 1 & 8 \\ -4 & -4 & 11 \end{pmatrix}$$

**Solution:**

$$1. \text{ For } A = \begin{pmatrix} 2 & -4 \\ -1 & 2 \end{pmatrix}$$

$\lambda=0$  and  $\lambda=4$  are the eigenvalues of  $A$ .

$$E_0(A)=\text{span}\left\{\begin{pmatrix} 2 \\ 1 \end{pmatrix}\right\} \text{ and } E_4(A)=\text{span}\left\{\begin{pmatrix} -2 \\ 1 \end{pmatrix}\right\}.$$

$X_1=\begin{pmatrix} 2 \\ 1 \end{pmatrix}$  and  $X_2=\begin{pmatrix} -2 \\ 1 \end{pmatrix}$  are linearly independent.

$$\text{Let } P=\begin{pmatrix} 2 & -2 \\ 1 & 1 \end{pmatrix}.$$

$$\text{Then } P^{-1}=\frac{1}{4}\begin{pmatrix} 1 & 2 \\ -1 & 2 \end{pmatrix}$$

$$\text{Hence, } D=P^{-1}AP=\begin{pmatrix} 0 & 0 \\ 0 & 4 \end{pmatrix}$$

$$2. \text{ For } A = \begin{pmatrix} 5 & 8 & 16 \\ 4 & 1 & 8 \\ -4 & -4 & 11 \end{pmatrix}$$

$\lambda=1$  and  $\lambda=-3$  (with multiplicity two) are the eigenvalues of  $A$ .

$$E_1(A)=\text{span}\left\{\begin{pmatrix} 2 \\ 1 \\ -1 \end{pmatrix}\right\} \text{ and } E_{-3}(A)=\text{span}\left\{\begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -2 \\ 0 \\ 1 \end{pmatrix}\right\}.$$

$X_1=\begin{pmatrix} 2 \\ 1 \\ -1 \end{pmatrix}$ ,  $X_2=\begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix}$  and  $X_3=\begin{pmatrix} -2 \\ 0 \\ 1 \end{pmatrix}$  are linearly independent.

$$\text{Let } P=\begin{pmatrix} 2 & -1 & -2 \\ 1 & 1 & 0 \\ -1 & 0 & 1 \end{pmatrix}.$$

$$\text{Then } P^{-1}=\begin{pmatrix} 1 & 1 & 2 \\ -1 & 0 & -2 \\ 1 & 1 & 3 \end{pmatrix}$$

Hence,

$$D=P^{-1}AP=\begin{pmatrix} 1 & 0 & 0 \\ 0 & -3 & 0 \\ 0 & 0 & -3 \end{pmatrix}$$

**Example 2.2.4:**

Consider the matrix

$$A = \begin{pmatrix} 2 & 1 & 1 \\ 2 & 1 & -2 \\ -1 & 0 & -2 \end{pmatrix}$$

$\lambda=3$  and  $\lambda=-1$  (with multiplicity two) are the eigenvalues of  $A$ .

$$E_3(A)=\text{span}\left\{\begin{pmatrix} 5 \\ 6 \\ -1 \end{pmatrix}\right\} \text{ and } E_{-1}(A)=\text{span}\left\{\begin{pmatrix} -1 \\ 2 \\ 1 \end{pmatrix}\right\}.$$

Any other eigenvector  $X_3$  of  $\lambda=-1$  is linearly dependent with respect to  $X_2$ . Then we cannot obtain an invertible matrix  $P$ . Hence  $A$  is not diagonalisable.

**Theorem 2.2.5:**

Let  $\lambda_1, \dots, \lambda_n$  be distinct eigenvalues of a square matrix. If  $X_1, \dots, X_n$  are the corresponding eigenvectors to  $\lambda_1, \dots, \lambda_n$ , then  $\{X_1, \dots, X_n\}$  is a linearly independent set.

**Proof:**

We apply mathematical induction on  $n$ ,

Step 1:  $n=1$ , clearly  $\{X_1\}$  is linearly independent, since it is a nonzero vector.

Step 2: Suppose it is true for all numbers less than  $n$ .

Step 3: For  $n$ , let

$$\sum_{i=1}^n b_i X_i = 0 \dots (1),$$

Then,

$$\sum_{i=1}^n b_i A X_i = 0,$$

Since  $A X_i = \lambda_i X_i$ , for all  $i=1, \dots, n$ , then

$$\sum_{i=1}^n b_i \lambda_i X_i = 0 \dots (2),$$

Let's multiply (1) by  $\lambda_1$ , then, we obtain

$$\sum_{i=1}^n b_i \lambda_1 X_i = 0 \dots (3),$$

Take (2)-(3), we obtain,

$$\sum_{i=2}^n b_i(\lambda_i - \lambda_1)X_i = 0 \dots (4),$$

From Step 2, we obtain,

$$b_i(\lambda_i - \lambda_1) = 0, \text{ for all } i=1, \dots, n.$$

Since  $\lambda_i$ , are distinct, for all  $i=1, \dots, n$ .

Then  $b_i=0$ , for all  $i=1, \dots, n$ .

**Theorem 2.2.6:**

A square matrix of order  $n$  with  $n$  distinct eigenvalues is diagonalisable.

**Remark 2.2.7:**

The converse of **Theorem 2.2.6** need not be true.

**Theorem 2.2.8:**

Let  $A$  be a square matrix of order  $n$  and

$$c_A(\lambda) = \prod_{i=1}^n (x - \lambda_i)^{m_i}$$

be the characteristic polynomial.

If  $d_i = \dim(E_{\lambda_i}(A))$ .

Then the following statements are equivalent:

1.  $A$  is diagonalisable
- 2.

$$\sum_{i=1}^n d_i = n, \forall i = 1, \dots, n.$$

3.  $d_i = m_i, \forall i$

**Example 2.2.9:**

Let

$$A = \begin{pmatrix} 2 & 0 & 0 & 0 \\ 4 & 2 & 0 & 0 \\ 7 & 3 & 3 & 0 \\ 2 & 6 & 4 & 1 \end{pmatrix}.$$

Prove that  $A$  is not diagonalisable.

**Exercise 2.2.10:**

i. Show that

$$A = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix}$$

is a diagonalisable matrix

ii. Show that

$$A = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix}$$

is not a diagonalisable matrix.

iii. Prove or disprove:

1. The sum of two diagonalisable matrices is diagonalisable.
2. If  $A$  is diagonalisable, then so is  $\lambda A$ ,  $\lambda \neq 0$ .

## Chapter 3: Inner product spaces, Orthogonality

### 3.1 Inner product spaces (Definition and examples)

#### Definition 3.1.1:

Let  $V$  be a vector spaces over a field  $\mathfrak{R}$ . An inner product on  $V$  is a function that assigns a number  $\langle u, v \rangle$  to every pairs  $u, v \in V$  such that the following axioms are satisfied:

3.  $\langle u, v \rangle = \langle v, u \rangle$ . (symmetric property)
4.  $\langle au+bw, v \rangle = a\langle u, v \rangle + b\langle w, v \rangle$ ,  $\forall a, b \in (\mathfrak{R} \text{ or } \mathbb{C})$ . (linear property)
5.  $\langle u, u \rangle > 0$ ,  $\forall u \neq 0$ . (positive definite property)

A vector space  $V$  with an inner product  $\langle \cdot, \cdot \rangle$  is called an inner product space.

Clearly,

$$\langle au-bw, v \rangle = a\langle u, v \rangle - b\langle w, v \rangle.$$

#### Example 3.1.2:

1. Consider the vector space  $\mathfrak{R}$  over  $\mathfrak{R}$ . Define  $\langle \cdot, \cdot \rangle$  on  $\mathfrak{R}$  as follows

$$\langle x, y \rangle = x \cdot y \text{ (The dot product)}$$

2. Consider the vector space  $\mathfrak{R}^2$  over  $\mathfrak{R}$ . Define  $\langle \cdot, \cdot \rangle$  on  $\mathfrak{R}$  as follows

$$\langle (x_1, y_1), (x_2, y_2) \rangle = x_1 \cdot x_2 + y_1 \cdot y_2 \text{ (The dot product)}$$

#### Example 3.1.3:

Consider the vector space  $\mathfrak{R}$  over  $\mathfrak{R}$ . Define  $\langle \cdot, \cdot \rangle$  as follows

$$\langle x, y \rangle = |x - y|.$$

$\langle x, y \rangle$  is not an inner product on  $\mathfrak{R}$ .

#### Example 3.1.4:

Let  $a, b \in \mathfrak{R}$ , define

$$C[a, b] = \{ f \mid f \text{ is continuous on the closed interval } [a, b] \}.$$

Define  $\langle , \rangle$  on  $C[a, b]$  as follows

$$\langle f, g \rangle = \int_a^b f(x)g(x)dx$$

Then  $\langle f, g \rangle$  is an inner product on  $C[a, b]$ .

**Example 3.1.5:**

In  $\mathfrak{R}^3$  and for every  $u$  and  $v \in \mathfrak{R}^3$ , If

$$\langle u, v \rangle = u^T A v, \text{ where}$$

$$A = \begin{pmatrix} 2 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 2 \end{pmatrix}.$$

Then  $\langle u, v \rangle$  is an inner product.

**Exercise 3.1.6:**

5. According to **Example 3.1.2, Task 2.**, how can we define an inner product on the vector space  $\mathfrak{R}^n$  over  $\mathfrak{R}$ ? Explain your answer.
6. Determine whether the following  $\langle , \rangle$  on the corresponding vector space is an inner product or not.
  - i.  $V = P_3$  with  $\langle p(x), q(x) \rangle = p(1)q(1)$
  - ii.  $V = C$  (the set of complex numbers) with  $\langle z, w \rangle = z\bar{w}$
  - iii.  $V = M_{2 \times 2}$  with  $\langle A, B \rangle = |AB|$

**Theorem 3.1.7:**

Let  $\langle , \rangle$  be an inner product on a vector space  $V$ . For any  $u, v, w \in V$  and  $a, b \in \mathfrak{R}$ .

1.  $\langle u, av+bw \rangle = a\langle u, v \rangle + b\langle u, w \rangle$
2.  $\langle au, v \rangle = a\langle u, v \rangle = \langle u, av \rangle$
3.  $\langle u, 0 \rangle = 0 = \langle 0, u \rangle$
4.  $\langle u, u \rangle = 0 \leftrightarrow u = 0$

**Proof:**

1.  $\langle u, av+bw \rangle = \langle av+bw, u \rangle = a\langle v, u \rangle + b\langle w, u \rangle = a\langle u, v \rangle + b\langle u, w \rangle.$



$$2. \langle au, v \rangle = \langle au + 0w, v \rangle = a\langle u, v \rangle + 0\langle w, v \rangle = a\langle u, v \rangle.$$

Similarly and by Task 1., we obtain  $a\langle u, v \rangle = \langle u, av \rangle$

$$3. \langle u, 0 \rangle = \langle u, 0+0 \rangle = \langle u, 1(0) + 1(0) \rangle = 1\langle u, 0 \rangle + 1\langle u, 0 \rangle = \langle u, 0 \rangle + \langle u, 0 \rangle$$

$$\langle u, 0 \rangle = \langle u, 0 \rangle + \langle u, 0 \rangle \rightarrow \langle u, 0 \rangle - \langle u, 0 \rangle = (\langle u, 0 \rangle + \langle u, 0 \rangle) - \langle u, 0 \rangle \rightarrow 0 = \langle u, 0 \rangle + 0$$

$$4. \langle u, u \rangle = 0 \rightarrow u = 0 \text{ by Definition 3.1.1.}$$

$$\text{For } u=0 \rightarrow \langle u, u \rangle = 0$$

### Example 3.1.8:

If  $u$  and  $v$  are vectors in an inner product space  $V$ , find

1.  $\langle 2u - 7v, 3u + 5v \rangle$
2.  $\langle 3u - 4v, 5u + v \rangle$  (Homework)

### Theorem 3.1.9:

In an inner product space  $V$ , for a vector  $u \in V$ , define,

$$W_u = \{v \in V \mid \langle u, v \rangle = 0\}.$$

Prove that  $W_u$  is a subspace of  $V$ .

#### Proof:

$W_u \neq \emptyset$  (why?)

Let  $a, b$  be scalars and  $v_1, v_2 \in W_u$ .

$$\langle u, av_1 + bv_2 \rangle = a\langle u, v_1 \rangle + b\langle u, v_2 \rangle = a(0) + b(0) = 0.$$

## 3.2 Normed vector space

### Definition 3.2.1

Let  $\langle \cdot, \cdot \rangle$  be an inner product on a vector space  $V$ .

1. The norm or the length of  $u \in V$  is defined as follows

$$\|u\| = \sqrt{\langle u, u \rangle}$$

2. The distance between two vectors  $u$  and  $v$  in  $V$  is defined as follows

$$d(u,v)=\|v-u\|$$

The pair  $(V, \|\cdot\|)$  is called a normed vector space.

**Example 3.2.2:**

In Example 3.1.2, find

1.  $\|x\|$  and  $\|x-y\|$
2.  $\|(x, y)\|$  and  $\|(x_1, y_1), (x_2, y_2)\|$

**Example 3.2.3:**

In Example 3.1.4, find

$$\|f\| \text{ and } \|f-g\|$$

**Theorem 3.2.4:**

Show that  $\langle u+v, u-v \rangle = \|u\|^2 - \|v\|^2$ .

**Proof:**

$$\|u\|^2 - \|v\|^2 = \langle u, u \rangle - \langle v, v \rangle = \langle u, u \rangle + \langle v, -v \rangle = \langle u+v, u-v \rangle.$$

**Definition 3.2.5:**

In an inner product space  $V$ , a vector  $u \in V$  is called a unit vector if  $\|u\|=1$

**Example 3.2.6:**

Let  $a, b > 0$ . In a vector space  $\mathfrak{R}^2$ , define

$$\langle (x, y), (x_1, y_1) \rangle = \frac{xx_1}{a^2} + \frac{yy_1}{b^2}.$$

1. Prove that  $\langle \cdot, \cdot \rangle$  is an inner product on  $\mathfrak{R}^2$ . (Homework)
2. Show that  $\|(x, y)\|=1 \Leftrightarrow \frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$

**Theorem 3.2.7 (Schwarz Inequality):**

In an inner product space  $V$ ,

$$\langle u, v \rangle^2 \leq \|u\|^2 \|v\|^2$$

**Proof:**

$$u=0 \vee v=0 \rightarrow \langle u, v \rangle = 0 \wedge (\|u\|=0 \vee \|v\|=0) \rightarrow 0 \leq 0$$

Let  $u \neq 0 \neq v$

$$0 \leq \|xu+v\|^2 = \langle xu+v, xu+v \rangle = x\langle u, xu+v \rangle + \langle v, xu+v \rangle$$

$$= x(x\langle u, u \rangle + \langle u, v \rangle) + x\langle v, u \rangle + \langle v, v \rangle = \langle u, u \rangle x^2 + \langle u, v \rangle 2x + \langle v, v \rangle$$

$$= \|u\|^2 x^2 + 2\langle u, v \rangle x + \|v\|^2 \rightarrow 4\langle u, v \rangle^2 \leq 4\|u\|^2 \|v\|^2 \rightarrow \langle u, v \rangle^2 \leq \|u\|^2 \|v\|^2$$

**Example 3.2.8:**

Apply **Schwarz Inequality** in **Example 3.1.4**.

**Theorem 3.2.9:**

Let  $\langle \cdot, \cdot \rangle$  be an inner product over  $V$  and  $u, v \in V$ .

1.  $\|u\| \geq 0$ .
2.  $\|u\|=0 \leftrightarrow u=0$
3.  $\|\lambda u\| = |\lambda| \|u\|$
4.  $\|u+v\| \leq \|u\| + \|v\|$  (**triangle inequality**)

**Proof:**

1. Straightforward.
2. Follows from **Theorem 3.1.7**, Task 4.
3.  $\|\lambda u\|^2 = \langle \lambda u, \lambda u \rangle = \lambda^2 \langle u, u \rangle \rightarrow \|\lambda u\| = |\lambda| \|u\|$
4.  $\|u+v\|^2 = \langle u+v, u+v \rangle = \langle u, u+v \rangle + \langle v, u+v \rangle = \langle u, u \rangle + \langle u, v \rangle + \langle v, u \rangle + \langle v, v \rangle$   
 $= \|u\|^2 + \langle u, v \rangle + \langle u, v \rangle + \|v\|^2 = \|u\|^2 + 2\langle u, v \rangle + \|v\|^2 \leq \|u\|^2 + 2\|u\| \|v\| + \|v\|^2 = (\|u\| + \|v\|)^2$   
 $\|u+v\|^2 \leq (\|u\| + \|v\|)^2 \rightarrow \|u+v\| \leq \|u\| + \|v\|$

**Theorem 3.2.10:**

If  $\langle \cdot, \cdot \rangle$  is an inner product on  $V$  and  $u_1, \dots, u_n$  is a spanning of  $V$ , then for each  $v \in V$ ,

$$\langle v, u_i \rangle = 0, \forall i=1, \dots, n \rightarrow v=0.$$

**Proof:**

$v = a_1u_1 + \dots + a_nu_n$ , for some scalars  $a_i, i=1, \dots, n$ .

$$\rightarrow \langle v, v \rangle = \langle v, a_1u_1 + \dots + a_nu_n \rangle \rightarrow \langle v, v \rangle = a_1\langle v, u_1 \rangle + a_2\langle v, u_2 \rangle + \dots + a_n\langle v, u_n \rangle = a_1(0) + \dots + a_n(0) = 0 \rightarrow v = 0.$$

**Theorem 3.2.11:**

Let  $V$  be an inner product space  $V$  and  $u, v$  be vectors in  $V$ .

1.  $d(u, v) \geq 0$ .
2.  $d(u, v) = 0 \Leftrightarrow u = v$
3.  $d(u, v) = d(v, u)$
4.  $d(u, v) \leq d(u, w) + d(w, v)$

**Proof:**

1. Follows from **Theorem 3.2.9, Task 1**.
2. Follows from **Theorem 3.2.9, Task 2**.
3.  $d(u, v) = \|u - v\| = \sqrt{\langle u - v, u - v \rangle} = \sqrt{\langle u, u \rangle - 2\langle u, v \rangle + \langle v, v \rangle}$   
 $d(v, u) = \|v - u\| = \sqrt{\langle v - u, v - u \rangle} = \sqrt{\langle v, v \rangle - 2\langle u, v \rangle + \langle u, u \rangle}$
4.  $d(u, v) = \|u - v\| = \|(u - w) + (w - v)\| \leq \|u - w\| + \|w - v\| \leq d(u, w) + d(w, v)$

**Exercise 3.2.12:**

- i. In an inner product space  $V$ , for  $u, v \in V$ , prove each of the following
  1.  $\|u + v\|^2 = \|u\|^2 + 2\langle u, v \rangle + \|v\|^2$
  2.  $\|u - v\|^2 = \|u\|^2 - 2\langle u, v \rangle + \|v\|^2$
  3.  $\langle u, v \rangle = 0.25(\|u + v\|^2 - \|u - v\|^2)$
- ii. In an inner product space  $V$ , let  $\|u\|=1, \|v\|=2$  and  $\|w\|=\sqrt{3}, \langle u, v \rangle = -1, \langle u, w \rangle = 0$  and  $\langle v, w \rangle = 3$ . Compute
  1.  $\langle v + w, 2u - v \rangle$
  2.  $\langle u - 2v - w, 3w - v \rangle$
- iii. Let  $T: V \rightarrow V$  be an isomorphism of the inner product space  $V$ . Show that  $\langle u, v \rangle^* = \langle T(u), T(v) \rangle$  is an inner product space on  $V$ .

### 3.3 Orthogonality

#### Definition 3.3.1:

Let  $V$  be an inner product space and  $u, v \in V$ . We say that  $u$  and  $v$  are orthogonal if

$$\langle u, v \rangle = 0$$

#### Definition 3.3.2:

Let  $V$  be an inner product space. A set  $\{u_1, \dots, u_n\}$  of vectors in  $V$  is called orthogonal if

1.  $u_i \neq 0, \forall i=1, \dots, n$
2. The set of vectors is pairwise orthogonal, that is  $\langle u_i, u_j \rangle = 0, \forall i \neq j$ .

Additionally, if  $\|u_i\|=1, \forall i$ , then the set  $\{u_1, \dots, u_n\}$  of vectors is called orthonormal.

#### Example 3.3.3:

1.  $(-1, 3)$  and  $(3, 1)$  are orthogonal with respect to **Example 3.1.2, Task 2**.
2.  $\sin x$  and  $\cos x$  are orthogonal in  $C[-\pi, \pi]$ .
3.  $(5, 2, -3)$  and  $(4, -1, 6)$  are orthogonal with respect to **Exercise 3.1.6, Task 1**.

#### Theorem 3.3.4 (The Pythagorean Theorem):

If  $\{u_1, \dots, u_n\}$  is an orthogonal set of vectors, then

$$\left\| \sum_{i=1}^n u_i \right\|^2 = \sum_{i=1}^n \|u_i\|^2.$$

#### Proof:

$$\begin{aligned} \|u_1 + \dots + u_n\|^2 &= \langle u_1 + \dots + u_n, u_1 + \dots + u_n \rangle = \langle u_1, u_1 \rangle + \langle u_2, u_2 \rangle + \dots + \langle u_n, u_n \rangle + \sum_{i \neq j} \langle u_i, u_j \rangle \\ &= \|u_1\|^2 + \dots + \|u_n\|^2 + 0 = \|u_1\|^2 + \dots + \|u_n\|^2 \end{aligned}$$

#### Theorem 3.3.5:

Let  $\{u_1, \dots, u_n\}$  be orthogonal set of vectors, then

- i.  $\{\lambda_1 u_1, \dots, \lambda_n u_n\}$  is orthogonal for every  $\lambda_i \neq 0$ .
- ii.  $\{\hat{u}_1, \dots, \hat{u}_n\}$  is orthonormal.

**Proof:**

i.

1. For each  $i=1, \dots, n$ ,  $u_i \neq 0 \rightarrow \lambda u_i \neq 0$ .
2.  $\langle \lambda u_i, \lambda u_j \rangle = \lambda \langle u_i, u_j \rangle = \lambda(0) = 0$ .

ii. Homework.

**Theorem 3.3.6:**

Every orthogonal set of vectors is linearly independent.

**Example 3.3.7:**

In **Example 3.1.5**, prove that

$$\left\{ \begin{pmatrix} 2 \\ -1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ -1 \\ 2 \end{pmatrix} \right\}$$

is an orthogonal basis of  $\mathfrak{R}^3$ , where

$$A = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 2 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

**Exercise 3.3.8:**

1. In an inner product space  $V$ , prove or disprove:
  - i.  $u, v \in V$  are orthogonal  $\leftrightarrow \|u+v\| = \|u-v\|$ .
  - ii.  $\{u, v\}$  is an orthogonal set  $\leftrightarrow \|u\| = \|v\|$ .
2. In **Example 3.1.5**, Verify whether

$$\left\{ \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ -6 \\ 1 \end{pmatrix} \right\}$$

is an orthogonal basis of  $\mathfrak{R}^3$  or not, where

$$A = \begin{pmatrix} 2 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 2 \end{pmatrix}.$$

### 3.4 Orthogonal projections

#### Definition 3.4.1:

Let  $W$  be a subspace of an inner product space  $V$ . The orthogonal complement  $W^\perp$  of  $W$  is defined as follows

$$W^\perp = \{v \in V \mid u \in W \rightarrow \langle u, v \rangle = 0\}$$

#### Theorem 3.4.2:

In an inner product space  $V$ , the orthogonal complement  $W^\perp$  of a subspace  $W$  of  $V$  is a subspace of  $V$ .

#### Proof:

$$u \in W \rightarrow \langle u, 0 \rangle = 0 \rightarrow 0 \in W^\perp.$$

Let  $v_1, v_2 \in W^\perp$ ,  $a, b$  be scalars and  $u \in W$ .

$$\langle u, av_1 + bv_2 \rangle = \langle u, av_1 \rangle + \langle u, bv_2 \rangle = a\langle u, v_1 \rangle + b\langle u, v_2 \rangle = a(0) + b(0) = 0 \rightarrow av_1 + bv_2 \in W^\perp.$$

#### Exercise 3.4.2:

Let  $U$  and  $W$  be a subspace of a vector space  $V$ . Define

$$U \oplus W = \{u + w \mid u \in U \wedge w \in W\}$$

Show that  $U \oplus W$  is a subspace of  $V$ .

#### Definition 3.4.3:

A vector space  $V$  is called a direct sum of subspaces  $U$  and  $W$  if

1.  $U \cap W = \{0\}$
2.  $V = U \oplus W$ .

#### Exercise 3.4.4:

Let  $V$  be a finite dimensional direct sum vector space of subspaces  $U$  and  $W$ . Then

$$\dim(V) = \dim(U) + \dim(W).$$

**Theorem 3.4.5:**

Let  $W$  be a finite dimensional subspace of an inner product space  $V$ , then  $V=W\oplus W^\perp$ .

**Proof:**

We will apply **Definition 3.4.3**,

1. Let  $v \in W \cap W^\perp$ . Since  $\langle v, v \rangle = 0$ , then  $v = 0$ .
2. Clearly,  $W \oplus W^\perp \subseteq V$ .

Let  $v \in V \rightarrow v = 0 + v$ . According to **Theorem 3.1.7, Task 3**,  $\langle v, 0 \rangle = 0$ , then  $v \in W^\perp$ .

**Theorem 3.4.6:**

Let  $V$  be an inner product space,  $U$  be the orthogonal complement of  $W$ . Define a function  $T: V \rightarrow V$  as follows

$$T(v) = u, \text{ where } v = u + w, u \in U, w \in W.$$

Then

1.  $T$  is a linear operator on  $V$ . ( $T$  is called the projection on  $U$  with kernel  $W$ )
2.  $\text{img}(T) = U$
3.  $\text{ker}(T) = W$